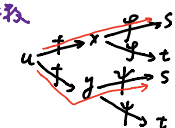


第十一章 多元函数微分学

§11.1 偏导数

链式法则:



$$\text{则 } \frac{\partial u}{\partial s} = \frac{\partial u}{\partial x} \cdot \frac{\partial x}{\partial s} + \frac{\partial u}{\partial y} \cdot \frac{\partial y}{\partial s}$$

f'_{xy} 与 f'_{yx} : 可能不等. 如 $f(x,y) = \begin{cases} xy \frac{x^2+y^2}{x^2+y^2} & x,y \neq 0 \\ 0 & x,y = 0 \end{cases}$

f'_x, f'_y 在某点的邻域内存在 且 f'_{xy} 在此点连续: $f'_{xy} = f'_{yx}$.

§11.2 全微分

<可微性定义> 存在 $\delta \Delta x, \Delta y$ 无关的常数 A, B , 使 $f(x_0 + \Delta x, y_0 + \Delta y) - f(x_0, y_0) = A \Delta x + B \Delta y + o(\sqrt{\Delta x^2 + \Delta y^2})$

偏导数连续 \Rightarrow 可微 \Rightarrow 连续 \Rightarrow 偏导数存在.
 \Rightarrow 任何方向的方向导数存在

复合函数: $\begin{cases} \text{一阶微分有形式不变性} \\ \text{高阶没有} \end{cases}$

$$u = f(x,y) \quad du = f'_x dx + f'_y dy \quad d^n u = \sum_{k=0}^n C_n^k \frac{\partial^n u}{\partial x^k \partial y^{n-k}} \Delta x^k \Delta y^{n-k}$$

$$d^2 f(x_1, \dots, x_n) = (dx_1, \dots, dx_n) \begin{pmatrix} \frac{\partial^2 u}{\partial x_1^2} & \dots & \frac{\partial^2 u}{\partial x_1 \partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial^2 u}{\partial x_n \partial x_1} & \dots & \frac{\partial^2 u}{\partial x_n^2} \end{pmatrix} \begin{pmatrix} dx_1 \\ \vdots \\ dx_n \end{pmatrix}$$

Hesse 矩阵.

$$\frac{\partial(f_1, \dots, f_m)}{\partial(x_1, \dots, x_n)} \triangleq \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \dots & \frac{\partial f_m}{\partial x_n} \end{pmatrix}_{m \times n}$$

Jacobian 矩阵.

§11.3 方向导数与梯度

<方向导数> $\frac{\partial f}{\partial \vec{l}}(x_0) = \lim_{\vec{l} \rightarrow x_0} \frac{f(\vec{l}) - f(x_0)}{|\vec{l} - x_0|}$ \vec{l} 是过 x_0 的一条射线, \vec{l} 代表其方向. 可微 \Rightarrow 任何方向的方向导数存在

$$\vec{l} = (\cos \alpha_1, \dots, \cos \alpha_n) \quad \text{其中 } \alpha_i \text{ 代表 } \vec{l} \text{ 在 } x \text{ 轴的投影} \quad \cos^2 \alpha_1 + \dots + \cos^2 \alpha_n = 1$$

$$\frac{\partial f}{\partial \vec{l}}(x_0) = f'_{x_1}(x_0) \cdot \cos \alpha_1 + f'_{x_2}(x_0) \cdot \cos \alpha_2 + \dots + f'_{x_n}(x_0) \cdot \cos \alpha_n = \langle \nabla f(x_0), \vec{l} \rangle \quad (\text{在 } |\vec{l}|=1 \text{ 且 } f \text{ 可微时})$$

<梯度> $\nabla f(x_1, \dots, x_n) = (f'_{x_1}, f'_{x_2}, \dots, f'_{x_n})$ 梯度运算法则: ∇ 导数形式一致

梯度: $\begin{cases} \text{以 } \frac{\partial f}{\partial \vec{l}} \text{ 达到 max 的方向} \\ \text{使函数变化最快的方向.} \end{cases}$

$$f(u_1, u_2, \dots, u_m) \xrightarrow{u_i = u_i(x_1, \dots, x_n)} g(x_1, x_2, \dots, x_n)$$

$$(g'_{x_1}, g'_{x_2}, \dots, g'_{x_n}) = (f'_{u_1}, f'_{u_2}, \dots, f'_{u_m}) \cdot \frac{\partial(u_1, u_2, \dots, u_m)}{\partial(x_1, x_2, \dots, x_n)}$$

§11.4 多元泰勒公式

$$f(x_0 + \Delta x) = f(x_0) + df(x_0) + \frac{1}{2!} d^2 f(x_0) + \dots + \frac{1}{m!} d^m f(x_0) + \begin{cases} o(|\Delta x|^m) & |\Delta x| \rightarrow 0 \\ \frac{1}{(m+1)!} d^{m+1} f(c) & c = x_0 + \theta(x - x_0) \quad 0 < \theta < 1 \end{cases}$$

特例: $m=2$ $f(x) = f(x_0) + \langle \nabla f(x_0), \Delta x \rangle + \frac{1}{2} \Delta x \cdot H_f(x_0) \cdot \Delta x^T + o(|\Delta x|^2)$ 或: $\frac{1}{2} \Delta x \cdot H_f(x_0 + \theta \Delta x) \cdot \Delta x^T$

§11.5 隐函数存在定理

▷ 方程 $f(x, y) = 0$

$$\left. \begin{array}{l} f(x_0, y_0) = 0 \\ f'_y(x_0, y_0) \neq 0 \\ f(x, y) \text{ 与 } f'_y(x, y) \text{ 在 } (x_0, y_0) \text{ 某邻域连续} \end{array} \right\} \Rightarrow \text{存在唯一} \begin{array}{l} \text{定义于 } B_\delta(x_0), \\ \text{取值于 } B_\eta(y_0) \text{ 的函数 } y(x), \text{ 满足: } \begin{cases} y_0 = y(x_0) \\ f(x, y(x)) = 0 \end{cases} \end{array}$$

$$+ f'_x(x, y) \text{ 在 } (x_0, y_0) \text{ 某邻域连续} \left\{ \Rightarrow y'(x) = -\frac{f'_x(x, y(x))}{f'_y(x, y(x))}$$

▷ 方程组 $\begin{cases} f_1(x_1, \dots, x_n, y_1, \dots, y_m) = 0 \\ \dots \\ f_m(x_1, \dots, x_n, y_1, \dots, y_m) = 0 \end{cases}$ $(x_0, y_0) = (x_{01}, \dots, x_{0n}, y_{01}, \dots, y_{0m})$ $F(x, y) = \begin{pmatrix} f_1(x, y) \\ \vdots \\ f_m(x, y) \end{pmatrix}$

$$\left. \begin{array}{l} (x_0, y_0) \text{ 满足方程组} \\ \frac{D(f_1, \dots, f_m)}{D(y_1, \dots, y_m)}(x_0, y_0) \neq 0 \\ \text{映射 } F \text{ 与 } F'_{y_1}, F'_{y_2}, \dots, F'_{y_m} \text{ 均在 } (x_0, y_0) \text{ 某邻域连续} \end{array} \right\} \Rightarrow \text{存在唯一映射 } Y = Y(X), \text{ 满足: } \begin{cases} Y_0 = Y(x_0) \\ Y_i = y_i(x_1, \dots, x_n) \\ Y \text{ 在 } x_0 \text{ 某邻域内连续} \end{cases}$$

$$+ F'_{x_1}, F'_{x_2}, \dots, F'_{x_n} \text{ 均在 } (x_0, y_0) \text{ 某邻域连续} \left\{ \Rightarrow \frac{\partial(y_1, y_2, \dots, y_m)}{\partial(x_1, x_2, \dots, x_n)} = - \left(\frac{\partial(f_1, f_2, \dots, f_m)}{\partial(y_1, y_2, \dots, y_m)} \right)^{-1} \cdot \frac{\partial(f_1, f_2, \dots, f_m)}{\partial(x_1, x_2, \dots, x_n)}$$

▷ 方程组 $\begin{cases} y_1 = f_1(x_1, \dots, x_n) \\ \vdots \\ y_n = f_n(x_1, \dots, x_n) \end{cases}$ $X = (x_1, \dots, x_n)$ $Y = (y_1, \dots, y_n)$ $Y = F(X) = \begin{pmatrix} f_1 \\ \vdots \\ f_n \end{pmatrix}$ $(x_0, y_0) = (x_{01}, \dots, x_{0n}, y_{01}, \dots, y_{0n})$

$$\left. \begin{array}{l} (x_0, y_0) \text{ 满足方程组} \\ \frac{D(f_1, \dots, f_n)}{D(x_1, \dots, x_n)}(x_0) \neq 0 \\ F \text{ 与 } F'_{x_1}, F'_{x_2}, \dots, F'_{x_n} \text{ 均在 } x_0 \text{ 某邻域连续} \end{array} \right\} \Rightarrow \text{存在唯一映射 } X = G(Y), \text{ 满足: } \begin{cases} X_i = g_i(y_1, \dots, y_n) \\ V = F(U) \quad U = F(V) \\ F(g_1, \dots, g_n) = Y \quad G(f_1, \dots, f_n) = X \end{cases}$$

$$+ G'_{y_1}, G'_{y_2}, \dots, G'_{y_n} \text{ 均在 } y_0 \text{ 某邻域连续} \left\{ \Rightarrow \frac{\partial(g_1, g_2, \dots, g_n)}{\partial(y_1, y_2, \dots, y_n)}(Y) = \left(\frac{\partial(f_1, f_2, \dots, f_n)}{\partial(x_1, x_2, \dots, x_n)} \right)^{-1}(X)$$

§11.6 曲线切线与曲面切平面

设 R^n 中的曲线 $\Gamma = \{X | X = X(t) = (x_1(t), x_2(t), \dots, x_n(t)), t \in [a, b]\}$
 其中 $X(t) \in C[a, b]$ ($\forall X_i(t) \in C[a, b]$)
 简单曲线: 除 a, b 外, Γ 上每点与 $[a, b]$ 一一对应
 简单闭曲线: $X(a) = X(b)$, 除此以外无自交点
 简单开曲线: $X(a) \neq X(b) \sim \dots$
 光滑曲线: 若 Γ 表示为 $X = X(t)$ $t \in [a, b]$
 有 $X^{(k)}(t) \in C[a, b]$ ($\forall X_i(t) \in C[a, b]$) 且 $X'(t) \neq 0$
 如 Γ 是闭曲线时还应满足 $X'(a) = X'(b)$
 则称 Γ 为光滑曲线

过 $(x_0, y_0, z_0) = (X(t_0), Y(t_0), Z(t_0))$ 的
 $P: \begin{cases} x = X(t) \\ y = Y(t) \\ z = Z(t) \end{cases}$ 切线: $\frac{x-x_0}{X'(t_0)} = \frac{y-y_0}{Y'(t_0)} = \frac{z-z_0}{Z'(t_0)}$
 法平面: $X'(t_0)(x-x_0) + Y'(t_0)(y-y_0) + Z'(t_0)(z-z_0) = 0$

$P: \begin{cases} F(x, y, z) = 0 \\ G(x, y, z) = 0 \end{cases}$ 切向 $\vec{t} = \left(\frac{\partial(F, G)}{\partial(y, z)}, \frac{\partial(F, G)}{\partial(z, x)}, \frac{\partial(F, G)}{\partial(x, y)} \right)$

$S: F(x, y, z) = 0$ 法向量 $\vec{n} = (F_x, F_y, F_z)$

切平面 $F_x \cdot (x-x_0) + F_y \cdot (y-y_0) + F_z \cdot (z-z_0) = 0$

法线 $\frac{x-x_0}{F_x} = \frac{y-y_0}{F_y} = \frac{z-z_0}{F_z}$

$S: \begin{cases} x = x(u, v) \\ y = y(u, v) \\ z = z(u, v) \end{cases} \quad \vec{n} = \left(\frac{\partial(y, z)}{\partial(u, v)}, \frac{\partial(z, x)}{\partial(u, v)}, \frac{\partial(x, y)}{\partial(u, v)} \right)$

§11.7 极值理论

无条件极值:

$$\begin{cases} x_0 \text{ 是极小值} \Rightarrow \nabla F(x_0) = 0 \text{ 且 } H_f(x_0) \geq 0 \\ x_0 \text{ 是极大值} \Rightarrow \nabla F(x_0) = 0 \text{ 且 } H_f(x_0) \leq 0 \\ \nabla F(x_0) = 0 \text{ 且 } H_f(x_0) > 0 \Rightarrow x_0 \text{ 是极小值} \\ \nabla F(x_0) = 0 \text{ 且 } H_f(x_0) < 0 \Rightarrow x_0 \text{ 是极大值} \\ \nabla F(x_0) = 0 \text{ 且 } H_f(x_0) \text{ 不过} \Rightarrow x_0 \text{ 不是极值} \end{cases}$$

条件极值: 条件为 $g_i(x) = 0$ 记 $L = f + \sum \lambda_i g_i$

$$\begin{cases} x_0 \text{ 是极小值} \Rightarrow \nabla L(x_0) = 0 \text{ 且 } H_L(x_0) \geq 0 \\ x_0 \text{ 是极大值} \Rightarrow \nabla L(x_0) = 0 \text{ 且 } H_L(x_0) \leq 0 \\ \nabla L(x_0) = 0 \text{ 且 } H_L(x_0) > 0 \Rightarrow x_0 \text{ 是极小值} \\ \nabla L(x_0) = 0 \text{ 且 } H_L(x_0) < 0 \Rightarrow x_0 \text{ 是极大值} \\ \nabla L(x_0) = 0 \text{ 且 } H_L(x_0) \text{ 不过} \Rightarrow x_0 \text{ 不是极值} \end{cases}$$



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练习 11.1

$$1. (1) z'_x = \frac{-\frac{y}{x^2}}{1+(\frac{y}{x})^2} - \frac{1}{y} \cdot 2x \cdot \sin x^2 = -\frac{y}{x^2 y^2} - \frac{2x \cdot \sin x^2}{y}$$

$$z'_y = \frac{\frac{1}{x}}{1+(\frac{y}{x})^2} - \frac{\cos x^2}{y^2} = \frac{x}{x^2+y^2} - \frac{\cos x^2}{y^2}$$

$$(2) z = e^{x \ln x - x \ln y} + e^{\frac{y}{x} \ln x} \quad z'_x = (\ln x + 1 - \ln y) e^{x \ln \frac{x}{y}} + y \left(\frac{1}{x^2} - \frac{\ln x}{x^2} \right) e^{\frac{y}{x} \ln x}$$

$$= (\ln \frac{x}{y} + 1) \cdot \left(\frac{x}{y} \right)^x + \frac{y}{x^2} (1 - \ln x) \cdot x^{\frac{y}{x}}$$

$$z'_y = -\frac{x}{y} e^{x \ln \frac{x}{y}} + \frac{\ln x}{x} \cdot e^{\frac{y}{x} \ln x} = -\left(\frac{x}{y} \right)^{x+1} + x^{\frac{y}{x}-1} \cdot \ln x$$

$$(3) u'_x = \frac{-x}{(x^2+y^2+z^2)^{\frac{3}{2}}} \quad u'_y = \frac{-y}{(x^2+y^2+z^2)^{\frac{3}{2}}} \quad u'_z = \frac{-z}{(x^2+y^2+z^2)^{\frac{3}{2}}}$$

$$(4) u'_x = \frac{1}{\sqrt{1-\frac{z^2}{x^2+y^2}}} \cdot z \cdot \frac{(-x)}{(x^2+y^2)^{\frac{3}{2}}} = \frac{-\lambda z}{(x^2+y^2)\sqrt{x^2+y^2-z^2}} \quad u'_y = \frac{-yz}{(x^2+y^2)\sqrt{x^2+y^2-z^2}}$$

$$u'_z = \frac{1}{\sqrt{1-\frac{z^2}{x^2+y^2}}} \cdot \frac{1}{\sqrt{x^2+y^2}} = \frac{1}{\sqrt{x^2+y^2-z^2}}$$

$$(5) u'_x = -2x \cdot e^{-(x^2+y^2+z^2)} \sin(ax+by+cz) + a e^{-(x^2+y^2+z^2)} \cos(ax+by+cz)$$

$$u'_y = -2y \cdot e^{-(x^2+y^2+z^2)} \sin(ax+by+cz) + b e^{-(x^2+y^2+z^2)} \cos(ax+by+cz)$$

$$u'_z = -2z \cdot e^{-(x^2+y^2+z^2)} \sin(ax+by+cz) + c e^{-(x^2+y^2+z^2)} \cos(ax+by+cz)$$

$$(6) u = e^{\ln x^y y^z z^x} = e^{y \ln x + z \ln y + x \ln z}$$

$$u'_x = x^y y^z z^x \left(\frac{y}{x} + \ln z \right) \quad u'_y = x^y y^z z^x \left(\frac{z}{y} + \ln x \right) \quad u'_z = x^y y^z z^x \left(\frac{x}{z} + \ln y \right)$$



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2. $x^2+y^2 \neq 0$ 时 $\exists B_\delta(x_0, y_0) \cap (0,0) \neq \emptyset$ 使 $\forall (x,y) \in B_\delta(x_0, y_0), f(x,y) = \frac{xy}{x^2+y^2}$

$$\therefore f'_x(x,y) = \frac{y(x^2+y^2) - xy \cdot 2x}{(x^2+y^2)^2} = \frac{y(y^2-x^2)}{(x^2+y^2)^2}$$

$x^2+y^2=0$ 时 $f'_x(x,y) = \lim_{\Delta x \rightarrow 0} \frac{f(\Delta x, 0) - f(0,0)}{\Delta x} = \lim_{\Delta x \rightarrow 0} \frac{\frac{\Delta x \cdot 0}{\Delta x^2+0} - 0}{\Delta x} = 0$

综上: $f'_x(x,y) = \begin{cases} \frac{y(y^2-x^2)}{(x^2+y^2)^2} & x^2+y^2 \neq 0 \\ 0 & x^2+y^2 = 0 \end{cases}$ 同理 $f'_y(x,y) = \begin{cases} \frac{x(x^2-y^2)}{(x^2+y^2)^2} & x^2+y^2 \neq 0 \\ 0 & x^2+y^2 = 0 \end{cases}$

3. $\frac{\partial u}{\partial x} = \frac{1}{2\sqrt{x}} \cdot \frac{1}{\sqrt{x}+\sqrt{y}}, \quad \frac{\partial u}{\partial y} = \frac{1}{2\sqrt{y}} \cdot \frac{1}{\sqrt{x}+\sqrt{y}}$

$$\therefore x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} = \frac{1}{2}(\sqrt{x}+\sqrt{y}) \cdot \frac{1}{\sqrt{x}+\sqrt{y}} = \frac{1}{2}$$

4. (1) $\frac{\partial u}{\partial t} = \frac{\partial u}{\partial x} \cdot \frac{\partial x}{\partial t} + \frac{\partial u}{\partial y} \cdot \frac{\partial y}{\partial t} + \frac{\partial u}{\partial z} \cdot \frac{\partial z}{\partial t} = (4x+z^2) \cdot 2\cos t - z \cdot (2t-1) - (zxz-y) \cdot 3e^{-t}$
 $= 2(8\sin t + 9e^{-2t})\cos t - 3(2t-1)e^{-t} - 3(12\sin t e^{-t} - t^2 + t - 1)e^{-t}$

(2) $\frac{\partial u}{\partial r} = \frac{\partial u}{\partial x} \cdot \frac{\partial x}{\partial r} + \frac{\partial u}{\partial y} \cdot \frac{\partial y}{\partial r} = (3x^2-y)\cos\theta + (3y^2-x)\sin\theta = 3r^2(\cos^3\theta + \sin^3\theta) - 2rs\sin\theta\cos\theta$

$$\frac{\partial u}{\partial \theta} = \frac{\partial u}{\partial x} \cdot \frac{\partial x}{\partial \theta} + \frac{\partial u}{\partial y} \cdot \frac{\partial y}{\partial \theta} = (3x^2-y)(-r\sin\theta) + (3y^2-x)r\cos\theta = 3r^3\sin\theta\cos\theta(\sin\theta - \cos\theta) - r^2\cos 2\theta$$

(3) $\frac{\partial u}{\partial r} = \frac{\partial u}{\partial x} \cdot \frac{\partial x}{\partial r} + \frac{\partial u}{\partial y} \cdot \frac{\partial y}{\partial r} + \frac{\partial u}{\partial z} \cdot \frac{\partial z}{\partial r} = \left(\frac{x}{\sqrt{x^2+y^2+z^2}} + \frac{1}{1+\frac{x^2+y^2}{z^2}} \cdot \frac{x}{z\sqrt{x^2+y^2}}\right) \sin\varphi\cos\theta + \left(\frac{y}{\sqrt{x^2+y^2+z^2}} + \frac{1}{1+\frac{x^2+y^2}{z^2}} \cdot \frac{y}{z\sqrt{x^2+y^2}}\right) \sin\varphi\sin\theta$
 $+ \left(\frac{z}{\sqrt{x^2+y^2+z^2}} + \frac{1}{1+\frac{x^2+y^2}{z^2}} \cdot \frac{(-\sqrt{x^2+y^2})}{z^2}\right) \cos\varphi = 1. \quad \therefore \frac{\partial u}{\partial \varphi} = 1$

$$\frac{\partial u}{\partial \theta} = -(\sin\varphi\cos\theta + \frac{\cos\varphi\cos\theta}{r})r\sin\varphi\sin\theta + (\sin\varphi\sin\theta + \frac{\cos\varphi\sin\theta}{r})r\sin\varphi\cos\theta = 0$$



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$$5. z'_x = y + f\left(\frac{y}{x}\right) + x \cdot \left(-\frac{y}{x^2}\right) \cdot f'\left(\frac{y}{x}\right) = y + f\left(\frac{y}{x}\right) - \frac{y}{x} f'\left(\frac{y}{x}\right)$$

$$z'_y = x + x \cdot \frac{1}{x} \cdot f'\left(\frac{y}{x}\right) = x + f'\left(\frac{y}{x}\right)$$

$$\therefore x \cdot z'_x + y \cdot z'_y = xy + x f\left(\frac{y}{x}\right) - y f'\left(\frac{y}{x}\right) + xy + y \cdot f'\left(\frac{y}{x}\right) = 2xy + x f\left(\frac{y}{x}\right) = xy + z$$

$$6. \frac{1}{z} S = \frac{y-x}{xy}, \quad t = \frac{z-x}{xz}$$

$$\frac{\partial u}{\partial x} = -\frac{1}{x^2} \cdot f'_s - \frac{1}{x^2} \cdot f'_t \quad \frac{\partial u}{\partial y} = \frac{1}{y^2} f'_s \quad \frac{\partial u}{\partial z} = \frac{1}{z^2} f'_t$$

$$\therefore x^2 \frac{\partial u}{\partial x} + y^2 \frac{\partial u}{\partial y} + z^2 \frac{\partial u}{\partial z} = -f'_s - f'_t + f'_s + f'_t = 0$$

$$7. (1) \frac{\partial u}{\partial x} = \frac{a}{ax+by+cz} \quad \frac{\partial^2 u}{\partial x^2} = \frac{-a^2}{(ax+by+cz)^2} \quad \frac{\partial^3 u}{\partial x^3} = \frac{2a^3}{(ax+by+cz)^3} \quad \frac{\partial^4 u}{\partial x^4} = \frac{-6a^4}{(ax+by+cz)^4}$$

$$\frac{\partial u}{\partial y} = \frac{b}{ax+by+cz} \quad \frac{\partial^2 u}{\partial y^2} = \frac{-b^2}{(ax+by+cz)^2} \quad \frac{\partial^3 u}{\partial x \partial y^2} = \frac{2ab^2}{(ax+by+cz)^3} \quad \frac{\partial^4 u}{\partial x^3 \partial y} = \frac{-6a^2 b^2}{(ax+by+cz)^4}$$

$$(2) \frac{\partial^r u}{\partial z^r} = xy(z+r)e^{x+y+z} \quad (u'_z = xy(z+1)e^{x+y+z}, u''_z = xy(z+2)e^{x+y+z}, \dots)$$

$$\frac{\partial^{g+r} u}{\partial y^g \partial z^r} = x(y+g)(z+r)e^{x+y+z}$$

$$\frac{\partial^{p+g+r} u}{\partial x^p \partial y^g \partial z^r} = (x+p)(y+g)(z+r)e^{x+y+z}$$



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$$8. \frac{\partial u}{\partial x_i} = \frac{\partial u}{\partial r} \cdot \frac{\partial r}{\partial x_i} = \frac{x_i}{r} \cdot f'(r)$$

$$\frac{\partial^2 u}{\partial x_i^2} = \frac{r - \frac{x_i^2}{r}}{r^2} f'(r) + \frac{x_i^2}{r^2} f''(r) = \left(\frac{1}{r} - \frac{x_i^2}{r^3}\right) f'(r) + \frac{x_i^2}{r^2} f''(r)$$

$$\therefore \sum_{i=1}^n \frac{\partial^2 u}{\partial x_i^2} = \frac{n}{r} f'(r) - \frac{r^2}{r^3} f'(r) + \frac{r^2}{r^2} f''(r) = f''(r) + \frac{n-1}{r} f'(r)$$

$$9. \frac{\partial u}{\partial s} = \frac{\partial u}{\partial x} \cdot \frac{\partial x}{\partial s} = e^s \frac{\partial u}{\partial x} \Rightarrow \frac{\partial^2 u}{\partial s^2} = e^s \frac{\partial u}{\partial x} + x e^s \frac{\partial^2 u}{\partial x^2} = x \frac{\partial u}{\partial x} + x^2 \frac{\partial^2 u}{\partial x^2}$$

$$\frac{\partial u}{\partial t} = \frac{\partial u}{\partial y} \cdot \frac{\partial y}{\partial t} = e^t \frac{\partial u}{\partial y} \Rightarrow \frac{\partial^2 u}{\partial t^2} = e^t \frac{\partial u}{\partial y} + y e^t \frac{\partial^2 u}{\partial y^2} = y \frac{\partial u}{\partial y} + y^2 \frac{\partial^2 u}{\partial y^2}$$

$$\therefore x^2 \frac{\partial^2 u}{\partial x^2} + y^2 \frac{\partial^2 u}{\partial y^2} + x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} = \frac{\partial^2 u}{\partial s^2} + \frac{\partial^2 u}{\partial t^2}$$



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练习 11.2

$$1. (1) \frac{\partial u}{\partial x} = yz \cos xz \quad \frac{\partial u}{\partial y} = \sin xz \quad \frac{\partial u}{\partial z} = xy \cos xz \Rightarrow du = yz \cos(xz) dx + \sin(xz) dy + xy \cos(xz) dz$$

$$(2) \frac{\partial u}{\partial x} = e^y \quad \frac{\partial u}{\partial y} = xe^y \Rightarrow du = e^y dx + xe^y dy$$

$$(3) \frac{\partial u}{\partial x} = x^y y^z z^x \left(\frac{y}{x} + \ln z \right); \frac{\partial u}{\partial y} = x^y y^z z^x \left(\frac{z}{y} + \ln x \right); \frac{\partial u}{\partial z} = x^y y^z z^x \left(\frac{x}{z} + \ln y \right)$$

$$\Rightarrow du = x^y y^z z^x \left[\left(\frac{y}{x} + \ln z \right) dx + \left(\frac{z}{y} + \ln x \right) dy + \left(\frac{x}{z} + \ln y \right) dz \right]$$

$$(4) \frac{\partial u}{\partial x} = \frac{x}{x^2+y^2+z^2+\sqrt{x^2+y^2+z^2}} \quad \frac{\partial u}{\partial y} = \frac{y}{x^2+y^2+z^2+\sqrt{x^2+y^2+z^2}} \quad \frac{\partial u}{\partial z} = \frac{z}{x^2+y^2+z^2+\sqrt{x^2+y^2+z^2}}$$

$$\Rightarrow du = \frac{1}{x^2+y^2+z^2+\sqrt{x^2+y^2+z^2}} (x dx + y dy + z dz)$$

$$2. (1) du = \frac{\partial f}{\partial t} \cdot \frac{\partial t}{\partial x} dx + \frac{\partial f}{\partial t} \cdot \frac{\partial t}{\partial y} dy = f'_t \cdot \frac{x}{\sqrt{x^2+y^2}} dx + f'_t \cdot \frac{y}{\sqrt{x^2+y^2}} dy = f'_t \cdot \frac{1}{\sqrt{x^2+y^2}} \cdot (x dx + y dy)$$

$$(2) dw = \left(\frac{\partial f}{\partial u} \cdot \frac{\partial u}{\partial x} + \frac{\partial f}{\partial v} \cdot \frac{\partial v}{\partial x} \right) dx + \left(\frac{\partial f}{\partial u} \cdot \frac{\partial u}{\partial y} + \frac{\partial f}{\partial v} \cdot \frac{\partial v}{\partial y} \right) dy + \left(\frac{\partial f}{\partial u} \cdot \frac{\partial u}{\partial z} + \frac{\partial f}{\partial v} \cdot \frac{\partial v}{\partial z} \right) dz$$

$$= (f'_u + zx f'_v) dx + (f'_u + zy f'_v) dy + (f'_u + zz f'_v) dz.$$

$$3. (1) \frac{\partial (f_1, f_2)}{\partial (x, y)} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

$$(2) \frac{\partial (f_1, f_2, f_3)}{\partial (u, v)} = \begin{pmatrix} \cos v & -u \sin v \\ \sin v & u \cos v \\ 0 & 1 \end{pmatrix} \quad (u, v) = (1, \pi) \text{ 时, 矩阵降为 } \begin{pmatrix} -1 & 0 \\ 0 & -1 \\ 0 & 1 \end{pmatrix}$$



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练习 11.3

$$1. \frac{\partial f}{\partial \vec{l}}(0,0) = \lim_{t \rightarrow 0} \frac{f(t \cos \theta, t \sin \theta) - f(0,0)}{t} = \lim_{t \rightarrow 0} \frac{(t \cos \theta)^3 + (t \sin \theta)^3}{t(t^2 \cos^3 \theta + t^2 \sin^3 \theta)} = \cos^3 \theta + \sin^3 \theta$$

注: f 在 0 处不可微, 不可应用 $\langle \nabla f, \vec{l} \rangle$.

$$2. \nabla f = (2x-y, 2y-x) \Big|_{(1,1)} = (1,1) \quad \vec{l} = (\cos \theta, \sin \theta) \quad \therefore \frac{\partial f}{\partial \vec{l}}(1,1) = \sin \theta + \cos \theta = \sqrt{2} \sin(\theta + \frac{\pi}{4})$$

$$(1) \theta = \frac{\pi}{4} \text{ 时 } \frac{\partial f}{\partial \vec{l}}(1,1) \text{ 最大. } \vec{l} = (\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2})$$

$$(2) \theta = \frac{5}{4}\pi \text{ 时 } \frac{\partial f}{\partial \vec{l}}(1,1) \text{ 最小. } \vec{l} = (-\frac{\sqrt{2}}{2}, -\frac{\sqrt{2}}{2})$$

$$(3) \theta = \frac{3}{4}\pi \text{ 或 } \frac{7}{4}\pi \text{ 时 } \frac{\partial f}{\partial \vec{l}}(1,1) \text{ 为 } 0. \quad \vec{l} = (-\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}) \text{ 或 } (\frac{\sqrt{2}}{2}, -\frac{\sqrt{2}}{2})$$

$$3. (1) \nabla u = (yz, xz, xy) \Big|_{(1,1,1)} = (1,1,1) \quad \text{模长为 } \sqrt{1^2+1^2+1^2} = \sqrt{3}$$

$$(2) \nabla u = (2x-y, 2y-x, 6z+b) \Big|_{(1,2,3)} = (0,3,24) \quad \text{模长为 } \sqrt{3^2+24^2} = 3\sqrt{65}$$

$$4. \nabla f = (ay^2+3cx^2z^2, 2axy+bz, by+2czx^3) \Big|_{(1,2,-1)} = (4a+3c, 4a-b, 2b-2c)$$

$$\vec{l} = (0,0,1) \quad \therefore \frac{\partial f}{\partial \vec{l}} = \langle \nabla f, \vec{l} \rangle = 2b-2c$$

$\therefore \nabla f$ 是方向导数的最大方向 $\therefore 4a+3c=0$ 且 $4a-b=0$ 时, $\frac{\partial f}{\partial \vec{l}}$ 取到最大值 64 .

$$\begin{cases} 4a+3c=0 \\ 4a-b=0 \\ 2b-2c=64 \end{cases} \Rightarrow \begin{cases} a=b \\ b=24 \\ c=-8 \end{cases}$$



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$$5. \frac{1}{r} = \frac{1}{\sqrt{x^2+y^2+z^2}} \quad \nabla \frac{1}{r} = \left(\frac{-x}{(x^2+y^2+z^2)^{\frac{3}{2}}}, \frac{-y}{(x^2+y^2+z^2)^{\frac{3}{2}}}, \frac{-z}{(x^2+y^2+z^2)^{\frac{3}{2}}} \right) = -\frac{1}{r^3}(x, y, z) = -\frac{1}{r^3} \vec{r}$$

$$6. \nabla u = - \left(\frac{x-a}{(x-a)^2+(y-b)^2+(z-c)^2}, \frac{y-b}{(x-a)^2+(y-b)^2+(z-c)^2}, \frac{z-c}{(x-a)^2+(y-b)^2+(z-c)^2} \right)$$

$$|\nabla u| = \frac{\sqrt{(x-a)^2+(y-b)^2+(z-c)^2}}{(x-a)^2+(y-b)^2+(z-c)^2} = \frac{1}{\sqrt{(x-a)^2+(y-b)^2+(z-c)^2}} \quad \text{当 } |\nabla u|=1 \text{ 时, } (x-a)^2+(y-b)^2+(z-c)^2=1.$$

即 以 (a, b, c) 为球心, 半径为 1 的球面上的点能使 $|\nabla u|=1$.

$$7. \begin{cases} x = r \sin \varphi \cos \theta \\ y = r \sin \varphi \sin \theta \\ z = r \cos \varphi \end{cases} \Rightarrow \begin{cases} r = \sqrt{x^2+y^2+z^2} \\ \varphi = \arccos \frac{z}{\sqrt{x^2+y^2+z^2}} \\ \theta = \arctan \frac{y}{x} \end{cases}$$

$$\therefore \nabla r = \frac{1}{\sqrt{x^2+y^2+z^2}}(x, y, z) \quad \therefore |\nabla r| = \frac{1}{\sqrt{x^2+y^2+z^2}} \cdot \sqrt{x^2+y^2+z^2} = 1$$

$$\therefore \nabla \varphi = -\frac{1}{\sqrt{1-\frac{z^2}{x^2+y^2+z^2}}} \cdot \left(\frac{-xz}{(x^2+y^2+z^2)^{\frac{3}{2}}}, \frac{-yz}{(x^2+y^2+z^2)^{\frac{3}{2}}}, \frac{x^2+y^2}{(x^2+y^2+z^2)^{\frac{3}{2}}} \right) = \frac{-1}{r^2 \sqrt{x^2+y^2}} (-xz, -yz, x^2+y^2)$$

$$\therefore |\nabla \varphi| = \frac{1}{r^2 \sqrt{x^2+y^2}} \cdot \sqrt{x^2 z^2 + y^2 z^2 + (x^2+y^2)^2} = \frac{1}{r} = \frac{1}{r_0}$$

$$\therefore \nabla \theta = \left(-\frac{y}{x^2} \cdot \frac{1}{1+\frac{y^2}{x^2}}, \frac{1}{x} \cdot \frac{1}{1+\frac{y^2}{x^2}}, 0 \right) = \left(-\frac{y}{x^2+y^2}, \frac{x}{x^2+y^2}, 0 \right)$$

$$\therefore |\nabla \theta| = \frac{1}{x^2+y^2} \sqrt{x^2+y^2} = \frac{1}{\sqrt{x^2+y^2}} = \frac{1}{r_0 \sin \varphi_0}$$



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练习 11.4.

$$1. (1) \nabla f = (-\sin x \cos y, -\cos x \sin y) \quad H_f = \begin{pmatrix} -\cos x \cos y & \sin x \sin y \\ \sin x \sin y & -\cos x \cos y \end{pmatrix}$$

$$\begin{aligned} \therefore f(x, y) &= f(0, 0) + \langle \nabla f, \Delta x \rangle + \frac{1}{2} \Delta x \cdot H_f \cdot \Delta x^T + o(\sqrt{x^2 + y^2}) \\ &= 1 + 0 + \frac{1}{2} (x, y) \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 1 - \frac{1}{2} x^2 - \frac{1}{2} y^2 + o(\sqrt{x^2 + y^2}) \end{aligned}$$

$$(2) \nabla f = \left(-\frac{\sin x}{\cos y}, \frac{\cos x \sin y}{\cos^2 y} \right) \quad H_f = \begin{pmatrix} -\frac{\cos x}{\cos y} & \frac{\sin x \sin y}{\cos^2 y} \\ \frac{\sin x \sin y}{\cos^2 y} & \frac{\cos x (1 + \sin^2 y)}{\cos^3 y} \end{pmatrix}$$

$$\therefore f(x, y) = 1 + 0 + \frac{1}{2} (x, y) \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 1 - \frac{1}{2} x^2 + \frac{1}{2} y^2 + o(\sqrt{x^2 + y^2})$$

$$(3) \nabla f = (4x - y - 6, 2y - x - 3) \quad H_f = \begin{pmatrix} 4 & -1 \\ -1 & 2 \end{pmatrix}$$

$$\begin{aligned} \therefore f(x, y) &= f(1, -2) + \langle (0, -8), (x-1, y+2) \rangle + \frac{1}{2} (x-1, y+2) \begin{pmatrix} 4 & -1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} x-1 \\ y+2 \end{pmatrix} \\ &= 13 - 8(x+2) + \frac{1}{2} [4(x-1)^2 + 2(y+2)^2 - 2(x-1)(y+2)] + o(\sqrt{(x-1)^2 + (y+2)^2}) \end{aligned}$$

$$2. \therefore \frac{\partial^k}{\partial y^k} f(x, y) = \frac{(-1)^{k-1} \cdot (k-1) e^x}{(y+1)^k} \quad \therefore \frac{\partial^n f}{\partial x^k \partial y^{n-k}} = \frac{(-1)^{n-k-1} \cdot (n-k-1) e^x}{(y+1)^{n-k-1}}$$

$$\therefore d^n f = \sum_{k=0}^n C_n^k \cdot \frac{\partial^n f}{\partial x^k \partial y^{n-k}} \cdot x^k \cdot y^{n-k} = \sum_{k=0}^n (-1)^{n-k-1} \cdot (n-k-1) \cdot C_n^k \cdot \frac{x^k \cdot y^{n-k} \cdot e^x}{(y+1)^{n-k-1}}$$

$$\therefore d^n f(0, 0) = \sum_{k=0}^n (-1)^{n-k-1} (n-k-1) C_n^k \cdot x^k \cdot y^{n-k} = \sum_{k=0}^n (-1)^{k-1} \cdot (k-1) C_n^k \cdot x^{n-k} y^k$$

$$\therefore f(x, y) = \sum_{n=1}^m \sum_{k=0}^n \frac{(-1)^{k-1} \cdot (k-1) C_n^k}{n!} \cdot x^{n-k} y^k + o(\sqrt{x^2 + y^2}^m)$$



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练习 1.5

1. (1) 设 $F(x, y, z) = x + y + z - e^{-(x+y+z)}$

$$F_x = F_y = F_z = 1 + e^{-(x+y+z)}$$

$$\therefore z_x = -\frac{F_x}{F_z} = -1, \quad z_y = -\frac{F_y}{F_z} = -1 \quad z_{xx} = z_{xy} = z_{yy} = 0$$

(2) 设 $F(x, y, z) = \sin(x+y) + \sin(y+z) - 1$

$$F_x = \cos(x+y) \quad F_y = \cos(x+y) + \cos(y+z) \quad F_z = \cos(y+z)$$

$$\therefore z_x = -\frac{F_x}{F_z} = -\frac{\cos(x+y)}{\cos(y+z)} \quad z_y = -\frac{F_y}{F_z} = -\frac{\cos(x+y) + \cos(y+z)}{\cos(y+z)} - 1$$

$$z_{xx} = \frac{\sin(x+y)}{\cos^2(y+z)} \quad z_{xy} = \frac{\sin(x+y)\cos(y+z) - \sin(y+z)\cos(x+y)}{\cos^2(y+z)}$$

$$z_{yy} = \frac{\sin(x+y)\cos(y+z) - \sin(y+z)\cos(x+y)}{\cos^2(y+z)} - 1$$

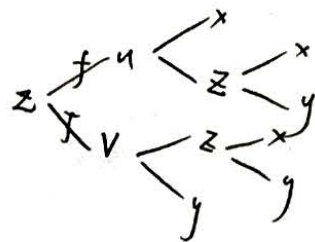


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练习 11.5.

2. (1) $dz = z_x dx + z_y dy$ 记 $u = xz$ $v = z - y$



$$\therefore z_x = f_u \cdot u_x + f_u \cdot u_z \cdot z_x + f_v \cdot v_z \cdot z_x = f_u \cdot z + f_u \cdot x \cdot z_x + f_v \cdot z_x = f_u(z + x z_x) + f_v \cdot z_x$$

$$\therefore (1 - f_u x - f_v) z_x = z f_u \quad \therefore z_x = \frac{z f_u}{1 - x f_u - f_v} \quad \text{同理 } z_y = \frac{f_v}{x f_u + f_v - 1}$$

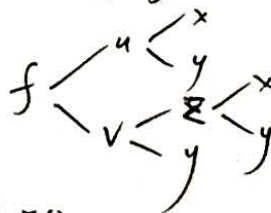
$$\therefore dz = \frac{-z f_u \cdot dx + f_v \cdot dy}{x f_u + f_v - 1}$$

(2) $\because f(x, y, z) = 0$ 令 $u = xy = u(x, y)$ $v = yz = v(x, y) = v(x, y)$

两边对 x 求导: $f(u, v) = 0$

$$f_u \cdot u_x + f_v \cdot v_z \cdot z_x = 0 \quad \therefore f_u \cdot y + f_v \cdot y \cdot z_x = 0$$

$$\therefore f_u + f_v \cdot z_x = 0 \quad \text{即 } f_u(u, v) + f_v(u, v) \cdot z_x = 0$$



两边对 x 求导: $f_{uu} \cdot u_x + f_{uv} \cdot v_z \cdot z_x + (f_{vu} \cdot u_x + f_{vv} \cdot v_z \cdot z_x) z_x + f_v \cdot z_{xx} = 0$

$$\therefore f_{uu} \cdot y + f_{uv} \cdot y \cdot z_x + (f_{uv} \cdot y + f_{vv} \cdot y \cdot z_x) z_x + f_v \cdot z_{xx} = 0$$

$$\therefore \frac{\partial^2 z}{\partial x^2} = z_{xx} = \frac{f_{uu} \cdot y + (f_{uv} \cdot y + f_{vv} \cdot y \cdot z_x) z_x + f_v \cdot y \cdot (z_x)^2}{-f_v}$$

$$= \frac{f_{uu} \cdot y + 2 f_{uv} \cdot y \cdot \frac{-f_u}{f_v} + f_{vv} \cdot y \cdot \left(\frac{f_u}{f_v}\right)^2}{-f_v}$$

$$= - \frac{y \cdot f_{uu} \cdot (f_v)^3 - 2 y f_u f_v f_{uv} + y \cdot f_{vv} (f_u)^2}{(f_v)^3}$$



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$$3. \quad \frac{\partial x}{\partial y} = -\frac{f_y}{f_x} \quad \frac{\partial y}{\partial z} = -\frac{f_z}{f_y} \quad \frac{\partial z}{\partial x} = -\frac{f_x}{f_z}$$

$$\therefore \frac{\partial x}{\partial y} \cdot \frac{\partial y}{\partial z} \cdot \frac{\partial z}{\partial x} = -\frac{f_y}{f_x} \cdot \frac{f_z}{f_y} \cdot \frac{f_x}{f_z} = -1$$

$$4. \quad \text{记 } F(x, y, z) = z^2 + xy - a, \quad G(x, y, z) = z^2 + x^2 - y^2 - b$$

$$\frac{\partial F}{\partial x} = y \quad \frac{\partial F}{\partial y} = x \quad \frac{\partial F}{\partial z} = 2z$$

$$\frac{\partial G}{\partial x} = 2x \quad \frac{\partial G}{\partial y} = -2y \quad \frac{\partial G}{\partial z} = 2z$$

$$(1) \quad \text{令 } \frac{D(F, G)}{D(x, y)} \neq 0 \quad \text{即 } \begin{vmatrix} \frac{\partial F}{\partial x} & \frac{\partial F}{\partial y} \\ \frac{\partial G}{\partial x} & \frac{\partial G}{\partial y} \end{vmatrix} \neq 0 \quad \text{即 } \begin{vmatrix} y & x \\ 2x & -2y \end{vmatrix} \neq 0$$

$$\therefore x+y \neq 0 \text{ 为条件.}$$

$$(2) \quad \text{令 } \frac{D(F, G)}{D(x, z)} \neq 0 \quad \text{即 } \begin{vmatrix} \frac{\partial F}{\partial x} & \frac{\partial F}{\partial z} \\ \frac{\partial G}{\partial x} & \frac{\partial G}{\partial z} \end{vmatrix} \neq 0 \quad \text{即 } \begin{vmatrix} y & 2z \\ 2x & 2z \end{vmatrix} \neq 0$$

$$\text{即 } z(y-2x) \neq 0 \text{ 为条件.}$$



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5.

(1) 后边组

对 x 求偏导:

$$\begin{cases} 2u \frac{\partial u}{\partial x} - \frac{\partial v}{\partial x} = 3 \\ 2u \frac{\partial u}{\partial x} - 4v \frac{\partial v}{\partial x} = 1 \end{cases} \Rightarrow \begin{cases} \frac{\partial v}{\partial x} = \frac{2}{4v-1} \\ \frac{\partial u}{\partial x} = \frac{12v-1}{2u(4v-1)} \end{cases}$$

对 y 求偏导:

$$\begin{cases} 2u \frac{\partial u}{\partial y} - \frac{\partial v}{\partial y} = 1 \\ 2u \frac{\partial u}{\partial y} - 4v \frac{\partial v}{\partial y} = -2 \end{cases} \Rightarrow \begin{cases} \frac{\partial v}{\partial y} = \frac{3}{4v-1} \\ \frac{\partial u}{\partial y} = \frac{2v+1}{u(4v-1)} \end{cases}$$

(2)

$$\frac{x}{y} = \frac{\cos \theta}{\sin \theta} = \frac{\cos \theta}{z} \quad \therefore \cos \theta = \frac{xz}{y} \quad \text{又} \sin \theta = z$$

$$\therefore z^2 + \frac{x^2 z^2}{y^2} = 1 \quad \text{即} \quad y^2 z^2 + x^2 z^2 = y^2$$

对 x 求偏导: $2z \cdot y^2 \frac{\partial z}{\partial x} + 2x \cdot z^2 + 2z \cdot x^2 \cdot \frac{\partial z}{\partial x} = 0$

$$\therefore 2z \cos^2 \varphi \frac{\partial z}{\partial x} = -2xz^2 \quad \therefore \frac{\partial z}{\partial x} = -\frac{\sin \theta \cos \theta}{\cos \varphi}$$

对 y 求偏导: $2y \cdot z^2 + 2z \cdot y^2 \frac{\partial z}{\partial y} + 2z \cdot x^2 \frac{\partial z}{\partial y} = 2y$

$$\therefore \cos^2 \varphi \frac{\partial z}{\partial y} = 2y - 2y \cdot z^2 \quad \therefore \frac{\partial z}{\partial y} = \frac{\cos^2 \theta}{\cos \varphi}$$



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练习 1.6

$$1. c) \frac{\partial x}{\partial t} = 2a \sin t \cos t \quad \frac{\partial y}{\partial t} = b(\cos^2 t - \sin^2 t) \quad \frac{\partial z}{\partial t} = -2c \sin t \cos t$$

$$x\left(\frac{\pi}{4}\right) = \frac{a}{2} \quad y\left(\frac{\pi}{4}\right) = \frac{b}{2} \quad z\left(\frac{\pi}{4}\right) = \frac{c}{2}$$

$$x'\left(\frac{\pi}{4}\right) = a \quad y'\left(\frac{\pi}{4}\right) = 0 \quad z'\left(\frac{\pi}{4}\right) = -c$$

$$\therefore \text{切线: } \frac{x - \frac{a}{2}}{a} = \frac{y - \frac{b}{2}}{0} = \frac{z - \frac{c}{2}}{-c}$$

$$\text{切平面: } a\left(x - \frac{a}{2}\right) - c\left(z - \frac{c}{2}\right) = 0$$

$$(2) \text{ 记 } F(x, y, z) = 3x^2y + yz + 4, \quad G(x, y, z) = 2xz - x^2y - 3$$

$$\therefore \frac{\partial F}{\partial x} = 6xy = -6 \quad \frac{\partial F}{\partial y} = 3x^2 + z = 4 \quad \frac{\partial F}{\partial z} = y = -1$$

$$\frac{\partial G}{\partial x} = 2z - 2xy = 4 \quad \frac{\partial G}{\partial y} = -x^2 = -1 \quad \frac{\partial G}{\partial z} = 2x = 2$$

$$\text{切线 } \vec{l} = \left\{ \frac{D(F, G)}{D(y, z)}, \frac{D(F, G)}{D(z, x)}, \frac{D(F, G)}{D(x, y)} \right\} = \left\{ \begin{vmatrix} 4 & -1 \\ -1 & 2 \end{vmatrix}, \begin{vmatrix} -1 & -6 \\ 2 & 4 \end{vmatrix}, \begin{vmatrix} -6 & 4 \\ 4 & -1 \end{vmatrix} \right\} = (7, 8, -10) \quad \text{代入点 } (1, -1, 1)$$

$$\text{切线: } \frac{x-1}{7} = \frac{y+1}{8} = \frac{z-1}{-10}$$

$$\text{法平面: } 7(x-1) + 8(y+1) - 10(z-1) = 0$$

$$(3) \text{ 记 } F(x, y, z) = x + y + z - 3 \quad G(x, y, z) = x^2 - y^2 + 2z^2 - 2$$

$$\therefore \frac{\partial F}{\partial x} = \frac{\partial F}{\partial y} = \frac{\partial F}{\partial z} = 1 \quad \frac{\partial G}{\partial x} = 2x = 2 \quad \frac{\partial G}{\partial y} = -2y = -2 \quad \frac{\partial G}{\partial z} = 4z = 4$$

$$\text{代入点 } (1, 1, 1) \text{ 点} \quad = 2 \quad = -2 \quad = 4$$

$$\text{切线 } \vec{l} = \left\{ \frac{D(F, G)}{D(y, z)}, \frac{D(F, G)}{D(z, x)}, \frac{D(F, G)}{D(x, y)} \right\} = \left\{ \begin{vmatrix} 1 & 1 \\ -2 & 4 \end{vmatrix}, \begin{vmatrix} 1 & 1 \\ 4 & 2 \end{vmatrix}, \begin{vmatrix} 1 & 1 \\ 2 & -2 \end{vmatrix} \right\} = (6, -2, -4)$$

$$\text{切线: } \frac{x-1}{6} = \frac{y+1}{-2} = \frac{z+1}{-4}$$

$$\text{法平面: } 6(x-1) - 2(y+1) - 4(z+1) = 0$$



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2. 证: $\frac{\partial x}{\partial t} = -a \sin t$ $\frac{\partial y}{\partial t} = a \cos t$ $\frac{\partial z}{\partial t} = b$ 切向 $\vec{l} = (-a \sin t, a \cos t, b)$

取坐标轴方向 $\vec{O}_z = (0, 0, 1)$ $\cos \langle \vec{l}, \vec{O}_z \rangle = \frac{\vec{l} \cdot \vec{O}_z}{|\vec{l}| \cdot |\vec{O}_z|} = \frac{b}{\sqrt{a^2 + b^2}}$

\therefore 无论 t 几何, $\langle \vec{l}, \vec{O}_z \rangle \equiv \arccos \frac{b}{\sqrt{a^2 + b^2}}$.

3. (1) 记 $F(x, y, z) = 2\frac{x}{z} + 2\frac{y}{z} - 8$

$\therefore F_x = 2 \cdot \frac{1}{z} \cdot \ln 2 \cdot \frac{1}{z}$ $F_y = 2 \cdot \frac{1}{z} \cdot \ln 2 \cdot \frac{1}{z}$ $F_z = 2 \cdot \frac{x}{z^2} \cdot \ln 2 \cdot \frac{-x}{z^2} + 2 \cdot \frac{y}{z^2} \cdot \ln 2 \cdot \frac{-y}{z^2}$

$\therefore (F_x, F_y, F_z)|_{(1, 2, 1)} = (4 \ln 2, 4 \ln 2, -16 \ln 2)$ 记曲面的法向为 $\vec{l} = (1, 1, -4)$

\therefore 切平面: $(x-2) + (y-2) - 4(z-1) = 0$ 法线: $\frac{x-2}{1} = \frac{y-2}{1} = \frac{z-1}{-4}$

(2) 记 $f(x, y) = \arctan \frac{y}{x}$ $f_x = \frac{-\frac{y}{x^2}}{1 + \frac{y^2}{x^2}}$ $f_y = \frac{\frac{1}{x}}{1 + \frac{y^2}{x^2}}$

$\therefore (-f_x, -f_y, 1)|_{(1, 1, \frac{\pi}{4})} = (\frac{1}{2}, -\frac{1}{2}, 1)$ 记曲面的法向为 $\vec{l} = (1, -1, 2)$

切平面: $(x-1) - (y-1) + 2(z - \frac{\pi}{4}) = 0$ 法线: $\frac{x-1}{1} = \frac{y-1}{-1} = \frac{z - \frac{\pi}{4}}{2}$

(3) $x^2 + y^2 = z^2 \cot^2 \alpha$ 记 $F(x, y, z) = x^2 \cot^2 \alpha + y^2 \cot^2 \alpha - z^2 = 0$, 记 $P_0(r_0 \cos \varphi_0, r_0 \sin \varphi_0, r_0 \cot \alpha)$
 $\therefore F_x = 2x \cot^2 \alpha$ $F_y = 2y \cot^2 \alpha$ $F_z = -2z$
 $\therefore (F_x, F_y, F_z)|_{P_0} = (2r_0 \cos \varphi_0 \cot^2 \alpha, 2r_0 \sin \varphi_0 \cot^2 \alpha, -2r_0 \cot \alpha)$ 记法向 $\vec{l} = (\cos \varphi_0 \cot \alpha, \sin \varphi_0 \cot \alpha, -1)$
 切平面: $\cos \varphi_0 \cot \alpha (x - r_0 \cos \varphi_0) + \sin \varphi_0 \cot \alpha (y - r_0 \sin \varphi_0) - (z - r_0 \cot \alpha) = 0$
 法线: $\frac{x - r_0 \cos \varphi_0}{\cos \varphi_0 \cot \alpha} = \frac{y - r_0 \sin \varphi_0}{\sin \varphi_0 \cot \alpha} = \frac{z - r_0 \cot \alpha}{-1}$

(4) $\frac{x}{y} = \frac{\cos \frac{z}{a}}{\sin \frac{z}{a}}$ 记 $F(x, y, z) = x \sin \frac{z}{a} - y \cos \frac{z}{a} = 0$ 记 $P_0(u_0 \cos v_0, u_0 \sin v_0, av_0)$
 $\therefore F_x = \sin \frac{z}{a}$ $F_y = -\cos \frac{z}{a}$ $F_z = \frac{x}{a} \cos \frac{z}{a} + \frac{y}{a} \sin \frac{z}{a}$
 记法向 $\vec{l} = (F_x, F_y, F_z)|_{P_0} = (\sin v_0, -\cos v_0, \frac{u_0}{a}) \Rightarrow (a \sin v_0, -a \cos v_0, u_0)$

切平面: $a \sin v_0 (x - u_0 \cos v_0) - a \cos v_0 (y - u_0 \sin v_0) + u_0 (z - av_0) = 0$

法线: $\frac{x - u_0 \cos v_0}{a \sin v_0} = \frac{y - u_0 \sin v_0}{-a \cos v_0} = \frac{z - av_0}{u_0}$



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4. 记 $z = f(x, y) \therefore f_x = 2x, f_y = 2y \quad \vec{n} = (-f_x, -f_y, 1) = (-2x, -2y, 1)$

曲面上过任一点 $P_0(x_0, y_0, z_0)$ 的法线为 $\frac{x-x_0}{-2x_0} = \frac{y-y_0}{-2y_0} = \frac{z-z_0}{1}$

① 若 $x_0^2 + y_0^2 \neq 0$ 代入点 $(0, 0, 0) \therefore \frac{1}{2} = \frac{1}{2} = -z_0 \quad z_0 = -\frac{1}{2}$

\therefore 满足 $\begin{cases} x_0^2 + y_0^2 = \frac{1}{2} \\ z_0 = -\frac{1}{2} \end{cases}$ 的点 P_0 符合条件

② 若 $x_0 = 0$ 且 $y_0 = 0$ 法线为 z 轴. 通过原点, 符合条件.

此时 $z_0 = x_0^2 + y_0^2 - 1 = -1 \therefore P_0(0, 0, -1)$ 亦符合条件.

5. 令 $F(x, y, z) = x^2 + y^2 + z^2 - 16 \quad G(x, y, z) = x^2 + (y-5)^2 + z^2 - 9$

$\vec{F} = (F_x, F_y, F_z) = (x, y, z) \quad \vec{G} = (G_x, G_y, G_z) = (x, y-5, z)$

令 $F = G \therefore y^2 = (y-5)^2 + 7 \therefore 10y = 32 \quad y = \frac{16}{5}$

$\therefore F$ 与 G 任一交点为 $P_0(x_0, \frac{16}{5}, z_0) \therefore F(P_0) = x_0^2 + z_0^2 - \frac{144}{25} = 0$

$\vec{F}|_{P_0}: \vec{G}|_{P_0} = (x_0, \frac{16}{5}, z_0) \cdot (x_0, -\frac{9}{5}, z_0)$

$= x_0^2 + z_0^2 - \frac{144}{25} = F(P_0) = 0.$

$\therefore F=0$ 与 $G=0$ 正交.



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练习 11.7

1. (1)

$$\begin{cases} f_x = y(x^2 + y^2 - 4) + 2x^2y = 0 \\ f_y = x(x^2 + y^2 - 4) + 2xy^2 = 0 \end{cases} \Rightarrow \begin{matrix} X_1(0,0) & X_2(0,2) & X_3(0,-2) & X_4(-2,0) & X_5(2,0) \\ X_6(1,1) & X_7(-1,1) & X_8(1,-1) & X_9(-1,-1) \end{matrix}$$

$$\therefore f(X_1) = f(X_2) = \dots = f(X_5) = 0 \quad f(X_6) = f(X_9) = -2 \quad f(X_7) = f(X_8) = 2$$

经检验, f 极小值为 -2 , 极大值为 2 (检验 X_6, X_9, X_7, X_8 时作矩阵正/负定性)

(2)

$$\begin{cases} f_x = \cos x - \sin x - \sin(x-y) = 0 \\ f_y = \sin(x-y) = 0 \end{cases} \Rightarrow X\left(\frac{\pi}{4} + k_1\pi, \frac{5}{4}\pi + k_2\pi\right) \quad k_1, k_2 \in \mathbb{Z}$$

$$f(X) = \sqrt{2} \sin\left(\frac{\pi}{2} + k_1\pi\right) + \cos[\pi + (k_2 - k_1)\pi]$$

当 k_1 为偶, k_2 为偶时, $f(X) = \sqrt{2} - 1$

k_1 为偶, k_2 为奇时, $f(X) = \sqrt{2} + 1$

k_1 为奇, k_2 为奇时, $f(X) = -\sqrt{2} + 1$

k_1 为奇, k_2 为偶时, $f(X) = -\sqrt{2} - 1$

经检验 f 极大值为 $1 + \sqrt{2}$
极小值为 $-1 - \sqrt{2}$

$$(3) \begin{cases} f_x = y \cdot \ln(x^2 + y^2) + \frac{2x^2y}{x^2 + y^2} = 0 \\ f_y = x \cdot \ln(x^2 + y^2) + \frac{2xy^2}{x^2 + y^2} = 0 \end{cases} \Rightarrow \begin{matrix} X_1(1,0) & X_2(-1,0) & X_3(0,1) & X_4(0,-1) \\ X_5\left(\frac{1}{\sqrt{2e}}, \frac{1}{\sqrt{2e}}\right) & X_6\left(\frac{1}{\sqrt{2e}}, -\frac{1}{\sqrt{2e}}\right) & X_7\left(-\frac{1}{\sqrt{2e}}, \frac{1}{\sqrt{2e}}\right) & X_8\left(-\frac{1}{\sqrt{2e}}, -\frac{1}{\sqrt{2e}}\right) \end{matrix}$$

$$f(X_1) = f(X_2) = f(X_3) = f(X_4) = 0$$

$$f(X_5) = f(X_8) = \frac{1}{2e} \quad f(X_6) = f(X_7) = -\frac{1}{2e}$$

经检验, f 极小值为 $-\frac{1}{2e}$, 极大值为 $\frac{1}{2e}$.



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2.

(1) 令 $L(x, y, z) = x - 2y + 2z + \lambda(x^2 + y^2 + z^2 - 1)$

$$\begin{cases} L_x = 1 + 2\lambda x = 0 \\ L_y = -2 + 2\lambda y = 0 \\ L_z = 2 + 2\lambda z = 0 \\ x^2 + y^2 + z^2 = 1 \end{cases}$$

$$\Rightarrow \begin{matrix} \lambda = \frac{3}{2} & P_1(\frac{1}{3}, \frac{2}{3}, -\frac{2}{3}) & f(P_1) = -3 \\ \lambda = -\frac{3}{2} & P_2(\frac{1}{3}, -\frac{2}{3}, \frac{2}{3}) & f(P_2) = 3 \end{matrix}$$

$$\therefore H_L = \begin{pmatrix} 2\lambda & 0 & 0 \\ 0 & 2\lambda & 0 \\ 0 & 0 & 2\lambda \end{pmatrix} \quad \text{特征值分别为 } 2\lambda, 4\lambda^2, 8\lambda^3$$

$$\therefore \lambda = \frac{3}{2} \text{ 时 } H_L > 0 \quad \therefore f(P_1) = -3 \text{ 为极大值}$$

$$\lambda = -\frac{3}{2} \text{ 时 } H_L < 0 \quad \therefore f(P_2) = 3 \text{ 为极大值}$$

(2) 令 $L(x, y, z) = xyz + \lambda(\frac{1}{x} + \frac{1}{y} + \frac{1}{z} - \frac{1}{a})$

$$\begin{cases} L_x = yz - \frac{\lambda}{x^2} = 0 \\ L_y = xz - \frac{\lambda}{y^2} = 0 \\ L_z = xy - \frac{\lambda}{z^2} = 0 \\ \frac{1}{x} + \frac{1}{y} + \frac{1}{z} = \frac{1}{a} \end{cases} \Rightarrow \lambda = 81a^4, x = y = z = 3a$$

$$\therefore H_L = \begin{pmatrix} \frac{2\lambda}{x^3} & \frac{z}{x} & \frac{y}{x} \\ \frac{z}{y^3} & \frac{2\lambda}{y^3} & \frac{y}{y} \\ \frac{y}{z^3} & \frac{x}{z} & \frac{2\lambda}{z^3} \end{pmatrix} \quad \text{特征值分别为 } \frac{2\lambda}{x^3}, \frac{4\lambda^2}{x^3y^3} - \frac{z^2}{a}, \frac{2\lambda}{a} + 2xyz + \frac{8\lambda^3}{x^3y^3z^3}$$

$$\text{代入上述结果: } 6a, 27a^2, 540a^3$$

$$\therefore a > 0 \quad \therefore H_L > 0 \quad \therefore f(3a, 3a, 3a) = 27a^3 \text{ 是 } f \text{ 的极小值}$$



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2. (3)

$$\text{记 } L(x, y, z) = xyz + \lambda_1(x^2 + y^2 + z^2 - 1) + \lambda_2(x + y + z)$$

$$\begin{cases} L_x = yz + 2\lambda_1 x + \lambda_2 = 0 & ① \\ L_y = xz + 2\lambda_1 y + \lambda_2 = 0 & ② \\ L_z = xy + 2\lambda_1 z + \lambda_2 = 0 & ③ \\ x^2 + y^2 + z^2 = 1 & ④ \\ xyz = 0 & ⑤ \end{cases}$$

由①②③, 两两作差:
$$\begin{cases} (2\lambda_1 - z)(x - y) = 0 \\ (2\lambda_1 - y)(x - z) = 0 \\ (2\lambda_1 - x)(y - z) = 0 \end{cases}$$

由④⑤, x, y, z 不可能同时相等.

1° $x = y \neq z$ 时

$$\begin{cases} 2xz = 0 \\ 2x^2 + z^2 = 1 \end{cases} \Rightarrow \begin{cases} ① x = \frac{\sqrt{6}}{6}, y = \frac{\sqrt{6}}{6}, z = -\frac{\sqrt{6}}{3}, \lambda_1 = \frac{\sqrt{6}}{12}, \lambda_2 = \frac{1}{6}, f(X_1) = -\frac{\sqrt{6}}{18} \\ ② x = -\frac{\sqrt{6}}{6}, y = -\frac{\sqrt{6}}{6}, z = \frac{\sqrt{6}}{3}, \lambda_1 = -\frac{\sqrt{6}}{12}, \lambda_2 = \frac{1}{6}, f(X_2) = \frac{\sqrt{6}}{18} \end{cases}$$

2° $x = z \neq y$ 时

$$\begin{cases} 2xy = 0 \\ 2x^2 + y^2 = 1 \end{cases} \Rightarrow \begin{cases} ③ x = \frac{\sqrt{6}}{6}, y = -\frac{\sqrt{6}}{3}, z = \frac{\sqrt{6}}{6}, \lambda_1 = \frac{\sqrt{6}}{12}, \lambda_2 = \frac{1}{6}, f(X_3) = -\frac{\sqrt{6}}{18} \\ ④ x = -\frac{\sqrt{6}}{6}, y = \frac{\sqrt{6}}{3}, z = -\frac{\sqrt{6}}{6}, \lambda_1 = -\frac{\sqrt{6}}{12}, \lambda_2 = \frac{1}{6}, f(X_4) = \frac{\sqrt{6}}{18} \end{cases}$$

3° $y = z \neq x$ 时

$$\begin{cases} 2yx = 0 \\ 2y^2 + x^2 = 1 \end{cases} \Rightarrow \begin{cases} ⑤ x = -\frac{\sqrt{6}}{3}, y = \frac{\sqrt{6}}{6}, z = \frac{\sqrt{6}}{6}, \lambda_1 = \frac{\sqrt{6}}{12}, \lambda_2 = \frac{1}{6}, f(X_5) = -\frac{\sqrt{6}}{18} \\ ⑥ x = \frac{\sqrt{6}}{3}, y = -\frac{\sqrt{6}}{6}, z = -\frac{\sqrt{6}}{6}, \lambda_1 = -\frac{\sqrt{6}}{12}, \lambda_2 = \frac{1}{6}, f(X_6) = \frac{\sqrt{6}}{18} \end{cases}$$

容易验证: $(\frac{\sqrt{6}}{6}, \frac{\sqrt{6}}{6}, -\frac{\sqrt{6}}{3}), (\frac{\sqrt{6}}{6}, -\frac{\sqrt{6}}{3}, \frac{\sqrt{6}}{6}), (-\frac{\sqrt{6}}{3}, \frac{\sqrt{6}}{6}, \frac{\sqrt{6}}{6})$ 为极小值点, 取得 \min 值 $-\frac{\sqrt{6}}{18}$
 $(-\frac{\sqrt{6}}{6}, -\frac{\sqrt{6}}{6}, \frac{\sqrt{6}}{3}), (-\frac{\sqrt{6}}{6}, \frac{\sqrt{6}}{3}, -\frac{\sqrt{6}}{6}), (\frac{\sqrt{6}}{3}, -\frac{\sqrt{6}}{6}, -\frac{\sqrt{6}}{6})$ 为极大值点, 取得 \max 值 $\frac{\sqrt{6}}{18}$



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3.

(1)

$$\begin{cases} f_x = -6y - 18x = 0 \\ f_y = 12 - 8y - 6x = 0 \end{cases} \Rightarrow \begin{cases} x_1 = -\frac{2}{3} \\ y_1 = 2 \end{cases} \quad \text{点 } P_1(-\frac{2}{3}, 2) \text{ 在区域 } D \text{ 内部}$$

P_1 是 D 内部唯一临界点; 又 $f_{xx} = -18$, $f_{xy} = -6$, $f_{yy} = -8$, $H_f = \begin{pmatrix} -18 & -6 \\ -6 & -8 \end{pmatrix}$

$\because |H_f| > 0$, $-18 < 0$ $\therefore f$ 在区域 D 内部取得极大值 $f(-\frac{2}{3}, 2) = 12$.

在区域 D 的边界上, 记 $L(x, y) = f(x, y) + \lambda(\frac{x^2}{4} + \frac{y^2}{9} - 1)$

$$\begin{cases} L_x = -6y - 18x + \frac{\lambda}{2}x = 0 \\ L_y = 12 - 8y - 6x + \frac{2}{9}\lambda y = 0 \\ \frac{x^2}{4} + \frac{y^2}{9} = 1 \end{cases} \Rightarrow \begin{cases} (\lambda - 36)x + 12y = 0 \\ 5 + x + (12 - 2\lambda)y = 0 \\ 9x^2 + 4y^2 = 36 \end{cases} \quad \text{解得:}$$

$$\lambda_1 = 36 \quad P_2(2, 0) \quad f(P_2) = -36$$

$$\lambda_2 = 36 - 18\sqrt{3} \quad P_3(-1, \frac{3}{2}\sqrt{3}) \quad f(P_3) = 2\sqrt{3} - 36$$

$$\lambda_3 = 36 + 18\sqrt{3} \quad P_4(-1, -\frac{3}{2}\sqrt{3}) \quad f(P_4) = -2\sqrt{3} - 36$$

$$H_L = \begin{pmatrix} \frac{\lambda}{2} - 18 & -6 \\ -6 & \frac{2}{9}\lambda - 8 \end{pmatrix} \quad |H_L| = 36 + \frac{1}{9}(\lambda - 36)^2 > 0, \quad \frac{\lambda}{2} - 18 > 0 \Leftrightarrow \lambda > 36$$

$H_L(\lambda_2) < 0$ $H_L(\lambda_3) > 0$ $\therefore f(P_3)$ 为极大值, $f(P_4)$ 为极小值.

$\because -36 - 2\sqrt{3} < -36 < 12$, $\therefore f(P_2)$ 不是 max/min

经过大小比较,

$$f_{\max} = f(-\frac{2}{3}, 2) = 12$$

$$f_{\min} = f(-1, -\frac{3}{2}\sqrt{3}) = -2\sqrt{3} - 36$$



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3. (2)

$$f(x, y, z) \leq x + y + 1 \leq \sqrt{2(x^2 + y^2)} + 1 \leq \sqrt{2}z + 1 = 1 + \sqrt{2} \quad (x = y = \frac{\sqrt{2}}{2}, z = 1 \text{ 时 "或" } z)$$

$$f(x, y, z) \geq x + y + x^2 + y^2 = (x + \frac{1}{2})^2 + (y + \frac{1}{2})^2 - \frac{1}{2} \geq -\frac{1}{2} \quad (x = -\frac{1}{2}, y = -\frac{1}{2}, z = \frac{1}{2} \text{ 时 "或" } z)$$

$$\therefore f_{\max} = 1 + \sqrt{2} \quad f_{\min} = -\frac{1}{2}$$

(3)

在D内部:

$$\begin{cases} f_x = a - \frac{x}{\sqrt{1-x^2-y^2}} = 0 \\ f_y = b - \frac{y}{\sqrt{1-x^2-y^2}} = 0 \end{cases}$$

$$\text{解得 } X_1(\frac{a}{\sqrt{a^2+b^2+1}}, \frac{b}{\sqrt{a^2+b^2+1}}) \quad X_2(\frac{a}{\sqrt{a^2+b^2+1}}, \frac{-b}{\sqrt{a^2+b^2+1}}) \quad X_3(\frac{-a}{\sqrt{a^2+b^2+1}}, \frac{b}{\sqrt{a^2+b^2+1}}) \quad X_4(\frac{-a}{\sqrt{a^2+b^2+1}}, \frac{-b}{\sqrt{a^2+b^2+1}})$$

$$f(X_1) = \sqrt{a^2+b^2+1} \quad f(X_2) = \frac{a^2-b^2+1}{\sqrt{a^2+b^2+1}} \quad f(X_3) = \frac{b^2-a^2+1}{\sqrt{a^2+b^2+1}} \quad f(X_4) = \frac{1-a^2-b^2}{\sqrt{a^2+b^2+1}}$$

在D边界: $x^2 + y^2 = 1$. 令 $x = \cos \theta, y = \sin \theta$

$$z = a \cos \theta + b \sin \theta = \sqrt{a^2+b^2} \sin(\theta + \varphi)$$

$$\therefore -\sqrt{a^2+b^2} \leq z \leq \sqrt{a^2+b^2}$$

在 $-\sqrt{a^2+b^2}, \sqrt{a^2+b^2}, f(X_1), f(X_2), f(X_3), f(X_4)$ 六者中, 最大者为 $\sqrt{a^2+b^2+1}$, 最小者为 $-\sqrt{a^2+b^2}$

容易验证它们分别是极大/极小值, 进而为最大/最小值.



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4.

解: 设 $f(x, y, z) = x^2 + y^2 + (z - c)^2$ 求 f 在条件 $z = \frac{x^2}{a^2} + \frac{y^2}{b^2}$ 下的最值

$$\text{记 } L(x, y, z) = x^2 + y^2 + (z - c)^2 + \lambda \left(z - \frac{x^2}{a^2} - \frac{y^2}{b^2} \right)$$

$$\begin{cases} L_x = 2x - \frac{2\lambda}{a^2}x = 0 \\ L_y = 2y - \frac{2\lambda}{b^2}y = 0 \\ L_z = 2(z - c) + 2\lambda = 0 \\ z = \frac{x^2}{a^2} + \frac{y^2}{b^2} \end{cases} \quad \text{解得 } X_1 \left(0, \frac{\pm bc}{1+b^2}, \frac{c}{1+b^2} \right)$$

$$X_2 \left(\frac{\pm ac}{1+a^2}, 0, \frac{c}{1+a^2} \right)$$

$$f(X_1) = \frac{b^2 c^2}{(b^2+1)^2} + \frac{c^2 b^4}{(b^2+1)^2} = \frac{b^2 c^2}{1+b^2} \quad f(X_2) = \frac{a^2 c^2}{1+a^2}$$

$$\because 0 < b < a$$

$\therefore f(X_1)$ 为极小值 (min) $f(X_2)$ 为极大值 (经检验)



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习题 11-A

$$1. \quad \frac{\partial u}{\partial x} = \frac{1}{1 + \left(\frac{x^2+y^2}{x-y}\right)^2} \cdot \frac{2x(x-y) - (x^2+y^2)}{(x-y)^2} = \frac{x^2-y^2-2xy}{(x-y)^2 + (x^2+y^2)^2}$$

$$\frac{\partial u}{\partial y} = \frac{1}{1 + \left(\frac{x^2+y^2}{x-y}\right)^2} \cdot \frac{2y(x-y) + x^2+y^2}{(x-y)^2} = \frac{x^2-y^2+2xy}{(x-y)^2 + (x^2+y^2)^2}$$

$$\therefore \frac{\sin 2u}{2} = \sin u \cos u = \frac{\tan u}{1 + \tan^2 u} = \frac{\frac{x^2+y^2}{x-y}}{1 + \left(\frac{x^2+y^2}{x-y}\right)^2} = \frac{(x-y)(x^2+y^2)}{(x-y)^2 + (x^2+y^2)^2}$$

$$\text{而 } x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} = \frac{x(x^2-y^2-2xy) + y(x^2-y^2+2xy)}{(x-y)^2 + (x^2+y^2)^2} = \frac{x^3+xy^2-x^2y-y^3}{(x-y)^2 + (x^2+y^2)^2} = \frac{(x-y)(x^2+y^2)}{(x-y)^2 + (x^2+y^2)^2}$$

$$\therefore x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} = \frac{\sin 2u}{2}$$

$$2. \quad \because u(r \cos \theta, r \sin \theta) = S(r) \sin \theta \text{ 为 } \therefore \frac{\partial u}{\partial \theta} = 0$$

$$\therefore \frac{\partial u}{\partial \theta} = \frac{\partial u}{\partial x} \cdot \frac{\partial x}{\partial \theta} + \frac{\partial u}{\partial y} \cdot \frac{\partial y}{\partial \theta} = -r \sin \theta f'(r \cos \theta) + r \cos \theta g'(r \sin \theta) = 0$$

$$\text{即: } y f'(x) = x g'(y) \text{ 恒成立. 即 } \frac{f'(x)}{x} = \frac{g'(y)}{y} \text{ 恒成立.}$$

$$\text{由 } x, y \text{ 任意性 } \frac{f'(x)}{x} = \frac{g'(y)}{y} = c$$

$$\therefore f'(x) = c \cdot x, \quad g'(y) = c \cdot y \quad \therefore f(x) = C_1 x^2 + C'', \quad g(y) = C_1 y^2 + C'''$$

$$\therefore u(x, y) = f(x) + g(y) = C_1 (x^2 + y^2) + C_2. \quad (C_1, C_2 \text{ 为任意常数}).$$



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$$3. \frac{\partial u}{\partial r} = \frac{\partial u}{\partial x} \cdot \frac{\partial x}{\partial r} + \frac{\partial u}{\partial y} \cdot \frac{\partial y}{\partial r} = f'(r \cos \theta) g(r \sin \theta) \cdot \cos \theta + g'(r \sin \theta) \cdot f(r \cos \theta) \cdot \sin \theta = 0.$$

$$\therefore x f'(x) \cdot g(y) + y g'(y) f(x) = 0. \quad \text{由 } x, y \text{ 任意性 (或取 } x=1 \text{ 或 } y=1 \text{)}:$$

$$\frac{x f'(x)}{f(x)} = - \frac{y g'(y)}{g(y)} = C$$

$$\therefore \frac{f'(x)}{f(x)} = \frac{C}{x} \Rightarrow \ln |f(x)| = C \cdot \ln |x| \Rightarrow f(x) = C' \cdot x^C$$

$$\frac{g'(y)}{g(y)} = -\frac{C}{y} \Rightarrow \ln |g(y)| = -C \cdot \ln |y| \Rightarrow g(y) = C'' \cdot \left(\frac{1}{y}\right)^C \quad \left. \begin{array}{l} \Rightarrow u(x, y) = C_1 \cdot \left(\frac{x}{y}\right)^{C_2} \\ (C_1, C_2 \text{ 为任意常数}) \end{array} \right\}$$

$$4. \text{充分性: 令 } g(\alpha) = \frac{f(\alpha x_1, \dots, \alpha x_n)}{\alpha^\lambda}.$$

$$\therefore \sum_{i=1}^n x_i \frac{\partial f}{\partial x_i}(x_1, \dots, x_n) = \lambda \cdot f(x_1, \dots, x_n) \quad \therefore \alpha \cdot \sum_{i=1}^n x_i \cdot \frac{\partial f}{\partial x_i}(\alpha x_1, \dots, \alpha x_n) = \lambda \cdot f(\alpha x_1, \dots, \alpha x_n)$$

$$\therefore g'(\alpha) = \frac{1}{\alpha^{\lambda+1}} \left[\alpha^\lambda \sum_{i=1}^n x_i \cdot \frac{\partial f}{\partial x_i}(\alpha x_1, \dots, \alpha x_n) - \lambda \alpha^{\lambda+1} \cdot f(\alpha x_1, \dots, \alpha x_n) \right] = 0$$

$$\therefore g(\alpha) \text{ 恒为常数. } \because g(1) = f(x_1, \dots, x_n) \quad \therefore g(\alpha) \equiv f(x_1, \dots, x_n). \quad f \text{ 是 } \lambda \text{ 次正齐次函数.}$$

必要性:

$$\therefore f(\alpha x_1, \dots, \alpha x_n) = \alpha^\lambda f(x_1, \dots, x_n). \quad \text{两边对 } \alpha \text{ 求导}$$

$$\therefore \sum_{i=1}^n x_i \cdot \frac{\partial f}{\partial x_i}(\alpha x_1, \dots, \alpha x_n) = \lambda \alpha^{\lambda-1} \cdot f(x_1, \dots, x_n)$$

$$\text{令 } \alpha = 1 \quad \therefore \sum_{i=1}^n x_i \cdot \frac{\partial f}{\partial x_i}(x_1, \dots, x_n) = \lambda \cdot f(x_1, \dots, x_n)$$



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$$5. \frac{\partial u}{\partial r} = \frac{\partial u}{\partial x} \cdot \frac{\partial x}{\partial r} + \frac{\partial u}{\partial y} \cdot \frac{\partial y}{\partial r} = f'_x \cos \theta + f'_y \sin \theta$$

$$\frac{\partial u}{\partial \theta} = \frac{\partial u}{\partial x} \cdot \frac{\partial x}{\partial \theta} + \frac{\partial u}{\partial y} \cdot \frac{\partial y}{\partial \theta} = -r \sin \theta f'_x + r \cos \theta f'_y$$

$$\frac{\partial u}{\partial r^2} = (f'_{xx} \cos \theta + f'_{xy} \sin \theta) \cos \theta + (f'_{xy} \cos \theta + f'_{yy} \sin \theta) \sin \theta = \cos^2 \theta f'_{xx} + \sin^2 \theta f'_{yy} + \sin 2\theta f'_{xy}$$

$$\frac{\partial u}{\partial \theta^2} = -r [\cos \theta f'_x + \sin \theta (-r \sin \theta f'_{xx} + r \cos \theta f'_{xy})] + r [-\sin \theta f'_y + \cos \theta (-r \sin \theta f'_{xy} + r \cos \theta f'_{yy})]$$

$$= r^2 \sin^2 \theta f'_{xx} + r^2 \cos^2 \theta f'_{yy} - r^2 \sin 2\theta f'_{xy} - r \cos \theta f'_x - r \sin \theta f'_y$$

$$= r^2 \sin^2 \theta f'_{xx} + r^2 \cos^2 \theta f'_{yy} - r^2 \sin 2\theta f'_{xy} - r \cdot \frac{\partial u}{\partial r}$$

$$\therefore \frac{\partial^2 u}{\partial r^2} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} + \frac{1}{r} \frac{\partial u}{\partial r} = (\cos^2 \theta + \sin^2 \theta) f'_{xx} + (\cos^2 \theta + \sin^2 \theta) f'_{yy} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}$$

$$6. \text{ 令 } s = \frac{x}{x^2+y^2}, \quad t = \frac{y}{x^2+y^2} \quad \therefore u(x,y) = f(s(x,y), t(x,y)). \quad f \begin{cases} s \\ t \end{cases} \begin{cases} x \\ y \end{cases}$$

$$\frac{\partial u}{\partial x} = \frac{\partial f}{\partial s} \cdot \frac{\partial s}{\partial x} + \frac{\partial f}{\partial t} \cdot \frac{\partial t}{\partial x} = f'_s \cdot \frac{y^2 - x^2}{(x^2+y^2)^2} - f'_t \cdot \frac{2xy}{(x^2+y^2)^2} \quad \frac{\partial u}{\partial y} = f'_t \cdot \frac{x^2 - y^2}{(x^2+y^2)^2} - f'_s \cdot \frac{2xy}{(x^2+y^2)^2}$$

$$\frac{\partial^2 u}{\partial x^2} = (f_{ss} \cdot \frac{y^2 - x^2}{(x^2+y^2)^2} + f_{st} \cdot \frac{2xy}{(x^2+y^2)^2}) \cdot \frac{y^2 - x^2}{(x^2+y^2)^2} + f_{ss} \cdot \frac{2x(x^2 - 3y^2)}{(x^2+y^2)^3} - (f_{st} \cdot \frac{y^2 - x^2}{(x^2+y^2)^2} - f_{tt} \cdot \frac{2xy}{(x^2+y^2)^2}) \cdot \frac{2xy}{(x^2+y^2)^2} - f'_t \cdot \frac{2y(y^2 - 3x^2)}{(x^2+y^2)^3}$$

$$\frac{\partial^2 u}{\partial y^2} = -(f_{ss} \cdot \frac{2xy}{(x^2+y^2)^2} + f_{st} \cdot \frac{x^2 - y^2}{(x^2+y^2)^2}) \cdot \frac{2xy}{(x^2+y^2)^2} - f_{ss} \cdot \frac{2x(x^2 - 3y^2)}{(x^2+y^2)^3} + (f_{st} \cdot \frac{2xy}{(x^2+y^2)^2} + f_{tt} \cdot \frac{x^2 - y^2}{(x^2+y^2)^2}) \cdot \frac{x^2 - y^2}{(x^2+y^2)^2} + f'_t \cdot \frac{2y(y^2 - 3x^2)}{(x^2+y^2)^3}$$

$$\therefore \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{(x^2 - y^2)^2 + 4x^2 y^2}{(x^2+y^2)^4} f_{ss} + \frac{(x^2 - y^2)^2 + 4x^2 y^2}{(x^2+y^2)^4} f_{tt} = \frac{1}{(x^2+y^2)^2} \left(\frac{\partial^2 f}{\partial s^2} + \frac{\partial^2 f}{\partial t^2} \right) = 0$$

$\therefore u$ 也是调和函数.



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7. $\frac{1}{2} u = xy, v = \frac{x^2 - y^2}{2}, g(x, y) = f(u, v)$

$$\therefore \frac{\partial g}{\partial x} = \frac{\partial f}{\partial u} \cdot y + \frac{\partial f}{\partial v} \cdot x$$

$$\frac{\partial g}{\partial y} = \frac{\partial f}{\partial u} \cdot x - \frac{\partial f}{\partial v} \cdot y$$

$$\therefore \frac{\partial^2 f}{\partial x^2} = \frac{\partial(\frac{\partial f}{\partial u})}{\partial u} \cdot \frac{\partial u}{\partial x} \cdot y + \frac{\partial(\frac{\partial f}{\partial u})}{\partial v} \cdot \frac{\partial v}{\partial x} \cdot x + \frac{\partial f}{\partial v} = \frac{\partial^2 f}{\partial u^2} y^2 + \frac{\partial^2 f}{\partial v^2} x^2 + \frac{\partial f}{\partial v}$$

$$\frac{\partial^2 f}{\partial y^2} = \frac{\partial(\frac{\partial f}{\partial u})}{\partial u} \cdot \frac{\partial u}{\partial y} \cdot x - \frac{\partial(\frac{\partial f}{\partial v})}{\partial v} \cdot \frac{\partial v}{\partial y} \cdot y - \frac{\partial f}{\partial v} = \frac{\partial^2 f}{\partial u^2} x^2 + \frac{\partial^2 f}{\partial v^2} y^2 - \frac{\partial f}{\partial v}$$

$$\therefore \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = \left(\frac{\partial^2 f}{\partial u^2} + \frac{\partial^2 f}{\partial v^2} \right) (x^2 + y^2) = x^2 + y^2$$

8. $\frac{\partial z}{\partial x} = \varphi\left(\frac{y}{x}\right) - \frac{y}{x} \cdot \varphi'\left(\frac{y}{x}\right) - \frac{y}{x^2} \psi'\left(\frac{y}{x}\right) \quad \frac{\partial z}{\partial y} = \varphi'\left(\frac{y}{x}\right) + \frac{1}{x} \psi'\left(\frac{y}{x}\right)$

$$\therefore \frac{\partial^2 z}{\partial x^2} = -\frac{y}{x^2} \varphi'\left(\frac{y}{x}\right) + \frac{y}{x^2} \varphi'\left(\frac{y}{x}\right) + \frac{y^2}{x^3} \varphi''\left(\frac{y}{x}\right) + \frac{2y}{x^3} \psi'\left(\frac{y}{x}\right) + \frac{y^2}{x^4} \psi''\left(\frac{y}{x}\right)$$

$$\frac{\partial^2 z}{\partial y^2} = \frac{1}{x} \varphi''\left(\frac{y}{x}\right) + \frac{1}{x^2} \psi''\left(\frac{y}{x}\right) \quad \frac{\partial^2 z}{\partial x \partial y} = -\frac{y}{x^2} \varphi''\left(\frac{y}{x}\right) - \frac{1}{x^2} \psi'\left(\frac{y}{x}\right) - \frac{y}{x^3} \psi'\left(\frac{y}{x}\right)$$

$$\therefore x^2 \frac{\partial^2 z}{\partial x^2} + 2xy \frac{\partial^2 z}{\partial x \partial y} + y^2 \frac{\partial^2 z}{\partial y^2} = \frac{y^2}{x} \varphi'' + \frac{2y}{x} \psi' + \frac{y^2}{x^2} \psi'' + \frac{y^2}{x} \varphi'' + \frac{y^2}{x^2} \psi'' - \frac{2y^2}{x} \varphi'' - \frac{2y}{x} \psi' - \frac{2y^2}{x^2} \psi'' = 0$$

9. 设 $X_0 = (x_{10}, x_{20}, \dots, x_{n0}) \quad Y_0 = (y_{10}, y_{20}, \dots, y_{n0}) \quad \therefore \varphi_Y(t) = f(x_{10} + t y_{10}, \dots, x_{n0} + t y_{n0})$

$$\therefore \varphi_Y'(t) = y_{10} \cdot f'_{x_1} + y_{20} \cdot f'_{x_2} + \dots + y_{n0} f'_{x_n}$$

$$\therefore \varphi_Y''(t) = y_{10} (y_{10} f''_{x_1 x_1} + y_{20} f''_{x_1 x_2} + \dots + y_{n0} f''_{x_1 x_n}) + \dots + y_{n0} (y_{10} f''_{x_n x_1} + \dots + y_{n0} f''_{x_n x_n})$$

$$\therefore \varphi_Y''(t) = Y_0 \cdot H_f(X_0) \cdot Y_0 > 0. \quad \text{由 } Y_0 \text{ 任意性知 } H_f(X_0) \text{ 正定.}$$



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10. 使用数学归纳法证明:

$$n=1 \text{ 时. } \because \frac{\partial u}{\partial y} = y'(z) \cdot \frac{x}{(1-y)^2}, \quad \frac{\partial u}{\partial x} = y'(z) \cdot \frac{1}{1-y}$$

$$\therefore \frac{\partial u}{\partial y} = \frac{x}{1-y} \cdot \frac{\partial u}{\partial x} = z \cdot \frac{\partial u}{\partial x} \text{ 或 } \tilde{z}.$$

$$n=k+1 \text{ 时. 假设 } \frac{\partial^{k+1} u}{\partial y^{k+1}} = \frac{\partial^{k+2}}{\partial x^{k+2}} \left(z^{k+1} \cdot \frac{\partial u}{\partial x} \right) \text{ 或 } \tilde{z}.$$

$$\begin{aligned} \text{则 } n=k \text{ 时. } \frac{\partial^k u}{\partial y^k} &= \frac{\partial}{\partial y} \left(\frac{\partial^{k+1} u}{\partial y^{k+1}} \right) = \frac{\partial}{\partial y} \frac{\partial^{k+2}}{\partial x^{k+2}} \left(z^{k+1} \frac{\partial u}{\partial x} \right) = \frac{\partial^{k+2}}{\partial x^{k+2}} \frac{\partial}{\partial y} \left(z^{k+1} \cdot \frac{\partial u}{\partial x} \right) \\ &= \frac{\partial^{k+2}}{\partial x^{k+2}} \left((k+1) z^{k+1} \cdot \frac{x}{(1-y)^2} \cdot \frac{\partial u}{\partial x} + z^{k+1} \cdot \frac{\partial^2 u}{\partial y \partial x} \right) \end{aligned}$$

$$\begin{aligned} \frac{\partial^{k+1}}{\partial x^{k+1}} \left(z^{k+1} \frac{\partial u}{\partial x} \right) &= \frac{\partial^{k+2}}{\partial x^{k+2}} \left(z^{k+1} \cdot \frac{\partial u}{\partial y} \right) = \frac{\partial^{k+2}}{\partial x^{k+2}} \cdot \frac{\partial}{\partial x} \left(z^{k+1} \cdot \frac{\partial u}{\partial y} \right) \\ &= \frac{\partial^{k+2}}{\partial x^{k+2}} \left((k+1) z^{k+1} \cdot \frac{1}{1-y} \cdot \frac{\partial u}{\partial y} + z^{k+1} \cdot \frac{\partial^2 u}{\partial x \partial y} \right) \end{aligned} \quad \text{对比两式:}$$

$$\therefore \frac{\partial u}{\partial y} = z \cdot \frac{\partial u}{\partial x} \text{ 且 } \frac{\partial^2 u}{\partial x \partial y} = \frac{\partial^2 u}{\partial y \partial x}. \quad \therefore \frac{\partial^k u}{\partial y^k} = \frac{\partial^{k+1}}{\partial x^{k+1}} \left(z^k \cdot \frac{\partial u}{\partial x} \right).$$

<注> Lagrange 公式: $u = y(z)$. $z = (x, y)$ 是方程 $z = x + y \cdot f(z)$ 确定的隐函数. 则 $\frac{\partial^n u}{\partial y^n} = \frac{\partial^{n+1}}{\partial x^{n+1}} \left(z^n \frac{\partial u}{\partial x} \right)$

$$\begin{aligned} 11. \text{必要性: } \because f(x, y) &= g(x)h(y) \quad \therefore f_x = g'(x)h(y) \quad f_y = g(x)h'(y) \quad f_{xy} = g'(x)h'(y) \\ \therefore f \cdot f_{xy} &= f_x \cdot f_y = g(x)h(y) \cdot g'(x)h'(y) \end{aligned}$$

$$\text{充分性: 令 } F = \frac{f_x}{f} \quad (f \neq 0) \quad \therefore F_y = \frac{f \cdot f_{xy} - f_x f_y}{f^2} = 0$$

$$\therefore F \text{ 与 } y \text{ 无关} \quad \therefore \text{记 } F = P(x) = \frac{f_x}{f} \quad \therefore f_{xy} = f_y \cdot P(x)$$



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$$\frac{\partial^2 f}{\partial x \partial y}(x_0, y_0) = \lim_{\Delta x \rightarrow 0} \frac{1}{\Delta x} \left[\lim_{\Delta y \rightarrow 0} \frac{1}{\Delta y} (f(x_0 + \Delta x, y_0 + \Delta y) - f(x_0 + \Delta x, y_0) - f(x_0, y_0 + \Delta y) + f(x_0, y_0)) \right]$$

$$\triangleq \varphi(\Delta x) = f(x_0 + \Delta x, y_0 + \Delta y) - f(x_0 + \Delta x, y_0)$$

$$\therefore \frac{1}{\Delta x \Delta y} [(f(x_0 + \Delta x, y_0 + \Delta y) - f(x_0 + \Delta x, y_0)) - (f(x_0, y_0 + \Delta y) - f(x_0, y_0))] \triangleq \Phi$$

$$= \frac{1}{\Delta x \Delta y} [\varphi(x_0 + \Delta x) - \varphi(x_0)] = \frac{1}{\Delta y} \varphi'(x_0 + \theta \Delta x) = \frac{1}{\Delta y} [f_x(x_0 + \theta \Delta x, y_0 + \Delta y) - f_x(x_0 + \theta \Delta x, y_0)]$$

(0 < \theta < 1)

因为 f_x 在 (x_0, y_0) 可微

$$\therefore f_x(x_0 + \theta \Delta x, y_0 + \Delta y) - f_x(x_0 + \theta \Delta x, y_0) = \Delta f_x = f_{xx}(x_0, y_0) \cdot \theta \Delta x + f_{xy}(x_0, y_0) \Delta y + o_1(\sqrt{\Delta x^2 + \Delta y^2})$$

$$f_x(x_0 + \theta \Delta x, y_0) - f_x(x_0, y_0) = \Delta f_x = f_{xx}(x_0, y_0) \theta \Delta x + o_2(\theta \Delta x)$$

$$\Phi = \frac{1}{\Delta y} [f_{xy}(x_0, y_0) \cdot \Delta y + o_1 - o_2] = f_{xy}(x_0, y_0) + o_1 - o_2$$

$$\text{即 } \Phi = f_{yx}(x_0, y_0) + o_1 - o_2$$

$$\therefore \lim_{\Delta x \rightarrow 0} \lim_{\Delta y \rightarrow 0} \Phi = f_{xy} = f_{yx}|_{x_0, y_0}$$



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14. 要证 $f_{xy}(x, y)$ 在 (x_0, y_0) 处连续 只需证 $\lim_{\substack{x \rightarrow x_0 \\ y \rightarrow y_0}} f_{xy}(x, y) = f_{xy}(x_0, y_0)$.

$$\Delta y = y - y_0 \quad \therefore f_{xy}(x_0, y_0) = \lim_{\Delta y \rightarrow 0} \frac{f_x(x_0, y_0 + \Delta y) - f_x(x_0, y_0)}{\Delta y}$$

$\because f_x$ 存在且由中值定理, $f_x(x_0, y_0 + \Delta y) - f_x(x_0, y_0) = \Delta y \cdot f_{xy}(x_0, y_0 + \theta \Delta y)$

$$\therefore \text{上式} = \lim_{\Delta y \rightarrow 0} f_{xy}(x_0, y_0 + \theta \Delta y) = \lim_{\substack{x \rightarrow x_0 \\ y \rightarrow y_0}} f_{xy}(x, y)$$

$\therefore f_{xy}(x, y)$ 在 (x_0, y_0) 连续 \Rightarrow 定理 $f_{xy}(x_0, y_0) = f_{yx}(x_0, y_0)$.



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15. 本题的实质是关于复合函数可微性的相关讨论。

以下内容节选自华师大《数学分析（下册）》p118-119.

如果证明了这个定理，那么本题结论的成立是自然的。抑或，可以仿照下述的证明思路来给出一个证明。

定理 17.5 若函数 $x = \varphi(s, t), y = \psi(s, t)$ 在点 $(s, t) \in D$ 可微, $z = f(x, y)$ 在点 $(x, y) = (\varphi(s, t), \psi(s, t))$ 可微, 则复合函数

$$z = f(\varphi(s, t), \psi(s, t))$$

在点 (s, t) 可微, 且它关于 s 与 t 的偏导数分别为

$$\begin{aligned} \frac{\partial z}{\partial s} \Big|_{(s, t)} &= \frac{\partial z}{\partial x} \Big|_{(x, y)} \frac{\partial x}{\partial s} \Big|_{(s, t)} + \frac{\partial z}{\partial y} \Big|_{(x, y)} \frac{\partial y}{\partial s} \Big|_{(s, t)}, \\ \frac{\partial z}{\partial t} \Big|_{(s, t)} &= \frac{\partial z}{\partial x} \Big|_{(x, y)} \frac{\partial x}{\partial t} \Big|_{(s, t)} + \frac{\partial z}{\partial y} \Big|_{(x, y)} \frac{\partial y}{\partial t} \Big|_{(s, t)}. \end{aligned} \quad (4)$$

证 由假设 $x = \varphi(s, t), y = \psi(s, t)$ 在点 (s, t) 可微, 于是

$$\Delta x = \frac{\partial x}{\partial s} \Delta s + \frac{\partial x}{\partial t} \Delta t + \alpha_1 \Delta s + \beta_1 \Delta t, \quad (5)$$

$$\Delta y = \frac{\partial y}{\partial s} \Delta s + \frac{\partial y}{\partial t} \Delta t + \alpha_2 \Delta s + \beta_2 \Delta t, \quad (6)$$

其中当 $\Delta s, \Delta t$ 趋于零时, $\alpha_1, \alpha_2, \beta_1, \beta_2$ 都趋向于零. 又由 $z = f(x, y)$ 在点 (x, y) 可微, 所以

$$\Delta z = \frac{\partial z}{\partial x} \Delta x + \frac{\partial z}{\partial y} \Delta y + \alpha \Delta x + \beta \Delta y, \quad (7)$$

其中当 $\Delta x, \Delta y \rightarrow 0$ 时, $\alpha, \beta \rightarrow 0$ (我们补充 α, β 之定义使当 $\Delta x = 0, \Delta y = 0$ 时, $\alpha = \beta = 0$), 将(5), (6)代入(7), 得

$$\begin{aligned} \Delta z &= \left(\frac{\partial z}{\partial x} + \alpha \right) \left(\frac{\partial x}{\partial s} \Delta s + \frac{\partial x}{\partial t} \Delta t + \alpha_1 \Delta s + \beta_1 \Delta t \right) \\ &\quad + \left(\frac{\partial z}{\partial y} + \beta \right) \left(\frac{\partial y}{\partial s} \Delta s + \frac{\partial y}{\partial t} \Delta t + \alpha_2 \Delta s + \beta_2 \Delta t \right). \end{aligned}$$

整理后

$$\Delta z = \left(\frac{\partial z}{\partial x} \cdot \frac{\partial x}{\partial s} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial s} \right) \Delta s + \left(\frac{\partial z}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial z}{\partial y} \frac{\partial y}{\partial t} \right) \Delta t + \bar{\alpha} \Delta s + \bar{\beta} \Delta t, \quad (8)$$

其中

$$\bar{\alpha} = \frac{\partial z}{\partial x} \alpha_1 + \frac{\partial z}{\partial y} \alpha_2 + \frac{\partial x}{\partial s} \alpha + \frac{\partial y}{\partial s} \beta + \alpha \alpha_1 + \beta \alpha_2, \quad (9)$$

$$\bar{\beta} = \frac{\partial z}{\partial x} \beta_1 + \frac{\partial z}{\partial y} \beta_2 + \frac{\partial x}{\partial t} \alpha + \frac{\partial y}{\partial t} \beta + \alpha \beta_1 + \beta \beta_2. \quad (10)$$

由于 $\varphi(s, t), \psi(s, t)$ 在点 (s, t) 可微, 因此它们在点 (s, t) 都连续, 即当 $\Delta s, \Delta t \rightarrow 0$ 时, 有 $\Delta x, \Delta y \rightarrow 0$. 从而也有 $\alpha \rightarrow 0, \beta \rightarrow 0$, 以及 $\alpha_1, \alpha_2, \beta_1, \beta_2 \rightarrow 0$. 于是在(9)、(10)式中, 当 $\Delta s, \Delta t \rightarrow 0$, 有 $\bar{\alpha} \rightarrow 0, \bar{\beta} \rightarrow 0$. 故由(8)式推得复合函数(3)可微并求得 z 关于 s 和 t 的偏导数(4).

这里公式(4)也称为链式法则.



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16. $\because F$ 在 x_0 可微 $\therefore F(x) - F(x_0) = J_F(x_0) \cdot \Delta x + o(\|\Delta x\|) = (J_F(x_0) + o(\frac{\|\Delta x\|}{\|\Delta x\|})) \cdot \Delta x$
 其中 $\Delta x = x - x_0$. $\oplus \lim_{\Delta x \rightarrow 0} o(\frac{\|\Delta x\|}{\|\Delta x\|}) = 0$ 知: 存在 x_0 的邻域 U , 使:
 当 $x \in U$ 时, $|o(\frac{\|\Delta x\|}{\|\Delta x\|})| \leq 1$. 进而 $\|F(x) - F(x_0)\| \leq (J_F(x_0) + 1) \cdot \|\Delta x\|$.

17. $\frac{\partial u}{\partial t} = \frac{\partial f}{\partial x} \cdot \cos \alpha + \frac{\partial f}{\partial y} \cdot \cos \beta + \frac{\partial f}{\partial z} \cdot \cos \gamma$
 $\therefore \frac{\partial}{\partial t} (\frac{\partial f}{\partial t}) = \cos \alpha \cdot (\cos \alpha \cdot f'_{xx} + \cos \beta \cdot f'_{yx} + \cos \gamma \cdot f'_{zx}) + \cos \beta \cdot (\cos \alpha \cdot f'_{xy} + \cos \beta \cdot f'_{yy} + \cos \gamma \cdot f'_{zy})$
 $+ \cos \gamma (\cos \alpha \cdot f'_{xz} + \cos \beta \cdot f'_{yz} + \cos \gamma \cdot f'_{zz}) = \vec{t} \cdot H_f \cdot \vec{t}^T$

18. (1) $\frac{\partial f}{\partial \vec{t}}(x) = \langle \nabla f(x), \vec{t} \rangle = \langle \nabla f(x), \sum_{i=1}^n \langle \vec{t}, \vec{e}_i \rangle \vec{e}_i \rangle = \sum_{i=1}^n \langle \vec{t}, \vec{e}_i \rangle \cdot \langle \nabla f(x), \vec{e}_i \rangle = \sum_{i=1}^n \langle \vec{t}, \vec{e}_i \rangle \cdot \frac{\partial f}{\partial \vec{e}_i}(x)$
 (2) $\sum_{i=1}^n (\frac{\partial f}{\partial x_i})^2 = \sum_{i=1}^n \langle \nabla f, \vec{e}_i \rangle^2 = \sum_{i=1}^n |\nabla f|^2 \cdot \cos^2 \alpha_i = |\nabla f|^2 \cdot \sum_{i=1}^n \cos^2 \alpha_i = |\nabla f|^2 \cdot \sum_{i=1}^n \cos^2 \beta_i = \sum_{i=1}^n (\frac{\partial f}{\partial \vec{e}_i})^2$
 $\vec{e}_i = (0, 0, \dots, 0, 1, 0, \dots, 0)_{(i)}$ $\alpha_i: \nabla f$ 与 \vec{e}_i 夹角 $\beta_i: \nabla f$ 与 \vec{t}_i 夹角.

(3) $\langle \nabla f, \vec{t}_i \rangle = \frac{\partial f}{\partial \vec{t}_i} \quad \nabla f = \sum_{i=1}^n \langle \nabla f, \vec{t}_i \rangle \vec{t}_i = \sum_{i=1}^n \frac{\partial f}{\partial \vec{t}_i} \cdot \vec{t}_i$

17. $(x, y) \in D$ 时结论显然成立. 不妨设 $(x, y) \in D^\circ$. 令 $\vec{t} = (\cos \theta, \sin \theta) = (\frac{x}{\sqrt{x^2+y^2}}, \frac{y}{\sqrt{x^2+y^2}})$. $t = 1 - \sqrt{x^2+y^2}$

$\because D^\circ$ 是凸区域. 由微分中值定理. $\exists \xi \in (0, t)$ 使:

$f(x+t\cos\theta, y+t\sin\theta) - f(x, y) = t\cos\theta \cdot f'_x(x+\xi\cos\theta, y+\xi\sin\theta) + t\sin\theta \cdot f'_y(x+\xi\cos\theta, y+\xi\sin\theta)$
 $= t \cdot \frac{\partial f}{\partial \vec{t}}(x+\xi\cos\theta, y+\xi\sin\theta)$

由于 $|\frac{\partial f}{\partial \vec{t}}| \leq 1$ 且 $f(x+t\cos\theta, y+t\sin\theta) = 0$. (注意到 $(x+t\cos\theta, y+t\sin\theta) \in \partial D$)

因此 $|f(x, y)| \leq t = 1 - \sqrt{x^2+y^2}$



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20. 对 $\forall X_1, X_2 \in D$. 设 $\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \in [-M, M]$, $M \in \mathbb{R}^+$, $X_1(x_1, y_1)$ $X_2(x_2, y_2)$

由于 f 偏导存在. $\lim_{t \rightarrow 0} \frac{f(X_1 + t(X_2 - X_1)) - f(X_1)}{t} = \frac{\partial f}{\partial x} \cos \theta + \frac{\partial f}{\partial y} \sin \theta$

$$\therefore 0 = \lim_{t \rightarrow 0} -2Mt \leq \lim_{t \rightarrow 0} f(X_1 + t(X_2 - X_1)) - f(X_1) \leq \lim_{t \rightarrow 0} 2Mt = 0$$

$\therefore D$ 是凸域 $\therefore t \rightarrow 0$ 时 $X_3 = X_1 + t(X_2 - X_1) \in D$

由于 X_1, X_2 任意性. 故 X_3 也有任意性.

$\therefore \forall \varepsilon > 0, \exists \delta > 0$ s.t. $\forall X_1, X_3 \in D: |X_3 - X_1| < \delta$, 总有 $|f(X_3) - f(X_1)| < \varepsilon$

$\therefore f(x, y)$ 在 D 上一致连续.

或:

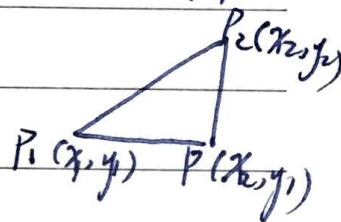
2. f 在 \mathbb{R}^2 上有连续偏导数 且 $|f_x(x, y)| \leq M$ $|f_y(x, y)| \leq M$

则对 $\forall P_1, P_2 \in \mathbb{R}^2$ 求证 $|f(P_1) - f(P_2)| \leq \sqrt{2} M \|P_1 - P_2\| = \sqrt{2} M \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$

$$|f(P_1) - f(P_2)| \leq |f(P_1) - f(P)| + |f(P) - f(P_2)|$$

由微分中值定理

$$\begin{aligned} f_x |x_1 - x_2| + f_y |y_1 - y_2| &\leq M(|x_1 - x_2| + |y_1 - y_2|) \\ &\leq \sqrt{2} M \cdot \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2} \end{aligned}$$



21. $D = \{(x, y) \in \mathbb{R}^2 \mid 1 < x^2 + y^2 < 4\}$ 为定义域

$$f(x, y) = \begin{cases} \arctan \frac{y}{x} & x > 0, y > 0 \\ \frac{\pi}{2} & x = 0, y > 0 \\ \pi + \arctan \frac{y}{x} & x < 0 \\ \frac{3\pi}{2} & x = 0, y < 0 \\ 2\pi + \arctan \frac{y}{x} & x > 0, y < 0 \end{cases}$$

$$f'_x(x, y) = -\frac{y}{x^2 + y^2} \quad f'_y(x, y) = \frac{x}{x^2 + y^2}$$

$$|f'_x| \leq 2, \quad |f'_y| \leq 2$$

$$\text{若取 } X_n = \left\{ \left(\frac{1}{2}, \frac{1}{n} \right) \right\} \quad Y_n = \left\{ \left(\frac{1}{2}, -\frac{1}{n} \right) \right\}$$

21) $\lim_{n \rightarrow \infty} |X_n - Y_n| = 0$ 但 $\lim_{n \rightarrow \infty} |f(X_n) - f(Y_n)| = 2\pi > 0$ 不连续.



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22 由之证: $u^2 + v^2 = 1$, $u_x' = v_y'$, $u_y' = -v_x'$.

$$\begin{cases} 2u \cdot u_x' + 2v \cdot v_x' = 0 \\ 2u \cdot u_y' + 2v \cdot v_y' = 0 \end{cases} \Rightarrow \begin{cases} u \cdot u_x' = -v \cdot v_x' \\ u \cdot u_y' = -v \cdot v_y' \end{cases} \Rightarrow \begin{cases} u \cdot u_x' = v \cdot u_y' \\ u \cdot v_x' = v \cdot v_y' \end{cases}$$

两式相乘 $u^2 \cdot u_x' v_x' = v^2 u_y' v_y' = (1 - u^2) u_y' v_y' = (u^2 - 1) u_x' v_x' \quad \therefore u_x' v_x' = 0$.

u_x', v_x' 中必有一者为零. 不妨设 $u_x' = 0$. $\therefore v_y' = 0$

$$\therefore \begin{cases} u \cdot u_y' = 0 \\ v \cdot v_x' = 0 \end{cases} \Rightarrow \because u^2 + v^2 = 1 \quad \therefore u, v \text{ 不可能在 } D \text{ 上同时恒为 } 0$$

\therefore 主 u, v 中一者不为零. 不妨设 u 不恒为零 $\therefore u_y' = 0 \quad \therefore v_x' = 0$

$\therefore u_x' = v_x' = u_y' = v_y' = 0 \quad \therefore u, v$ 在 D 上恒为常数.



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23. 题目修正为 $f(x,y)$ 在 $(0,0)$ 的邻域内二阶偏导数连续. (单点不能展开)

由多元 Taylor 公式

$$f(2h, e^{-\frac{1}{2h}}) = f(0,0) + [f'_x(0,0) \cdot 2h + f'_y(0,0) \cdot e^{-\frac{1}{2h}}] \\ + \frac{1}{2} [f''_{xx}(2\theta_1 h, \theta_1 e^{-\frac{1}{2h}}) \cdot 4h^2 + 2f''_{xy}(2\theta_1 h, \theta_1 e^{-\frac{1}{2h}}) \cdot 2he^{-\frac{1}{2h}} + f''_{yy}(2\theta_1 h, \theta_1 e^{-\frac{1}{2h}}) \cdot e^{-\frac{1}{h}}] \quad 0 < \theta_1 < 1$$

$$f(h, e^{-\frac{1}{h}}) = f(0,0) + [f'_x(0,0) \cdot h + f'_y(0,0) \cdot e^{-\frac{1}{h}}] \\ + \frac{1}{2} [f''_{xx}(\theta_2 h, \theta_2 e^{-\frac{1}{h}}) \cdot h^2 + 2f''_{xy}(\theta_2 h, \theta_2 e^{-\frac{1}{h}}) \cdot he^{-\frac{1}{h}} + f''_{yy}(\theta_2 h, \theta_2 e^{-\frac{1}{h}}) \cdot e^{-\frac{2}{h}}] \quad 0 < \theta_2 < 1$$

$$\therefore f(2h, e^{-\frac{1}{2h}}) - 2f(h, e^{-\frac{1}{h}}) + f(0,0)$$

$$= f'_y(0,0) \cdot (\underbrace{e^{-\frac{1}{2h}} - 2e^{-\frac{1}{h}}}_{\div h^2 f_{\eta_2} \rightarrow 0}) + 2h^2 f''_{xx}(\xi_1, \eta_1) - h^2 f''_{xx}(\xi_2, \eta_2)$$

$$\text{由于 } \lim_{h \rightarrow 0^+} \frac{e^{-\frac{1}{h}}}{h^2} = \lim_{x \rightarrow +\infty} \frac{x^2}{e^x} = 0$$

$$+ 2h \left[\underbrace{e^{-\frac{1}{2h}} f''_{xy}(\xi_1, \eta_1) - e^{-\frac{1}{h}} f''_{xy}(\xi_2, \eta_2)}_{\div h^2 f_{\eta_2} \rightarrow 0} \right] + \left[\underbrace{f''_{yy}(\xi_1, \eta_1) \cdot e^{-\frac{1}{h}} - f''_{yy}(\xi_2, \eta_2) \cdot e^{-\frac{2}{h}}}_{\div h^2 f_{\eta_2} \rightarrow 0} \right]$$

$$\therefore \lim_{h \rightarrow 0^+} \frac{f(2h, e^{-\frac{1}{2h}}) - 2f(h, e^{-\frac{1}{h}}) + f(0,0)}{h^2} = f''_{xx}(0,0)$$

24. 记 $f(x,y) = x - y - \varphi(y)$

$\therefore \varphi(0) = 0 \quad \therefore f(0,0) = 0$

$\therefore \varphi'(y) \in C(-a,a)$

$\therefore f(x,y) \in C B_\delta(0), f_x = 1 \in C B_\delta(0), f_y = -1 - \varphi'(y) \in C B_\delta$

$\text{且 } f_y(0,0) = -1 - \varphi'(0) < 0$

$f(0,0) = 0$

$f_y(0,0) \neq 0$

f, f_x, f_y 在 $(0,0)$ 连续

\Rightarrow 由隐函数存在定理 $\exists \delta > 0$.
在 $|x| < \delta$ 时有唯一可微函数 $y = y(x)$
满足 $x = y(x) + \varphi(y(x))$ 且 $y(0) = 0$



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A-25

1) 对 u 求偏导:

$$\Rightarrow \begin{cases} 2x \cdot \frac{\partial x}{\partial u} - \frac{\partial y}{\partial u} \cos(uv) + y v \sin(uv) + 2z \frac{\partial z}{\partial u} = 0 \\ 2x \cdot \frac{\partial x}{\partial u} + 2y \cdot \frac{\partial y}{\partial u} - v \cos(uv) + 4z \frac{\partial z}{\partial u} = 0 \\ \frac{\partial x}{\partial u} y + x \frac{\partial y}{\partial u} - \cos u \cos v + \frac{\partial z}{\partial u} = 0 \end{cases}$$

当 $x=y=1, z=0, u=\frac{\pi}{2}, v=0$

代入得 $\Rightarrow \begin{cases} 2 \frac{\partial x}{\partial u} \Big|_{(\frac{\pi}{2}, 0)} - \frac{\partial y}{\partial u} \Big|_{(\frac{\pi}{2}, 0)} = 0 \\ \frac{\partial x}{\partial u} \Big|_{(\frac{\pi}{2}, 0)} + \frac{\partial y}{\partial u} \Big|_{(\frac{\pi}{2}, 0)} = 0 \\ \frac{\partial x}{\partial u} \Big|_{(\frac{\pi}{2}, 0)} + \frac{\partial y}{\partial u} \Big|_{(\frac{\pi}{2}, 0)} + \frac{\partial z}{\partial u} \Big|_{(\frac{\pi}{2}, 0)} = 0 \end{cases}$ 解得 $\Rightarrow \frac{\partial x}{\partial u} \Big|_{(\frac{\pi}{2}, 0)} = 0$

2) 对 v 求偏导

$$\Rightarrow \begin{cases} 2x \frac{\partial x}{\partial v} - \frac{\partial y}{\partial v} \cos(uv) + y u \sin(uv) + 2z \frac{\partial z}{\partial v} = 0 \\ 2x \frac{\partial x}{\partial v} + 2y \cdot \frac{\partial y}{\partial v} - u \cos(uv) + 4z \frac{\partial z}{\partial v} = 0 \\ y \frac{\partial x}{\partial v} + x \frac{\partial y}{\partial v} + \sin u \cdot \sin v + \frac{\partial z}{\partial v} = 0 \end{cases}$$

$p_0(1, 1, 0, \frac{\pi}{2}, 0)$

代入得 $\Rightarrow \begin{cases} 2 \frac{\partial x}{\partial v} \Big|_{p_0} - \frac{\partial y}{\partial v} \Big|_{p_0} = 0 \\ 2 \frac{\partial x}{\partial v} \Big|_{p_0} + 2 \frac{\partial y}{\partial v} \Big|_{p_0} - \frac{\pi}{2} = 0 \\ \frac{\partial x}{\partial v} \Big|_{p_0} + \frac{\partial y}{\partial v} \Big|_{p_0} + \frac{\partial z}{\partial v} \Big|_{p_0} = 0 \end{cases}$ 解得 $\Rightarrow \frac{\partial x}{\partial v} \Big|_{p_0} = \frac{\pi}{12}$



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26.

$$\begin{cases} \frac{dx}{dt} = \frac{dr}{dt} \cos \theta - r \sin \theta \frac{d\theta}{dt} \\ \frac{dy}{dt} = \frac{dr}{dt} \sin \theta + r \cos \theta \frac{d\theta}{dt} \end{cases}$$

$$\text{又} \because \begin{cases} x^2 + y^2 = r^2 \\ x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

$$\therefore \text{原方程组可化为} \Rightarrow \begin{cases} \frac{dr}{dt} \cos \theta - r \sin \theta \frac{d\theta}{dt} = r \sin \theta + k r^3 \cos \theta \\ \frac{dr}{dt} \sin \theta + r \cos \theta \frac{d\theta}{dt} = -r \cos \theta + k r^3 \sin \theta \end{cases} \Rightarrow \begin{cases} \frac{dr}{d\theta} = k r^3 \\ \frac{d\theta}{dt} = -1 \end{cases}$$

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$$\therefore z e^z = x e^x + y e^y$$

$$\textcircled{1} \frac{\partial z}{\partial x} \cdot e^z + z e^z \frac{\partial z}{\partial x} = (1+x) e^x$$

$$\therefore \frac{\partial z}{\partial x} = \frac{(1+x) e^x}{(1+z) e^z}$$

$$\therefore \frac{\partial u}{\partial x} = \frac{(1 + \frac{\partial z}{\partial x})(y+z) - (x+z) \frac{\partial z}{\partial x}}{(y+z)^2} = \frac{(y-x) \frac{\partial z}{\partial x}}{(y+z)^2} + \frac{1}{y+z} = \frac{(y-x)(1+x) e^x}{(y+z)^2 (1+z) e^z} + \frac{1}{y+z}$$

$$\textcircled{2} \frac{\partial z}{\partial y} e^z + z e^z \frac{\partial z}{\partial y} = (1+y) e^y$$

$$\therefore \frac{\partial z}{\partial y} = \frac{(1+y) e^y}{(1+z) e^z}$$

$$\therefore \frac{\partial u}{\partial y} = \frac{\frac{\partial z}{\partial y} (y+z) - (x+z) (1 + \frac{\partial z}{\partial y})}{(y+z)^2} = \frac{(y-x) \frac{\partial z}{\partial y}}{(y+z)^2} - \frac{x+z}{(y+z)^2} = \frac{(y-x)(1+y) e^y}{(y+z)^2 (1+z) e^z} - \frac{x+z}{(y+z)^2}$$



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28. 对三个方程分别对 x , 对 y , 对 z 求偏导?

$$\text{对 } x \text{ 求: } \begin{cases} 1 = f_u \frac{\partial u}{\partial x} + f_v \frac{\partial v}{\partial x} + f_w \frac{\partial w}{\partial x} \\ 0 = g_u \frac{\partial u}{\partial x} + g_v \frac{\partial v}{\partial x} + g_w \frac{\partial w}{\partial x} \\ 0 = h_u \frac{\partial u}{\partial x} + h_v \frac{\partial v}{\partial x} + h_w \frac{\partial w}{\partial x} \end{cases}$$

$$\text{记 } D = \begin{vmatrix} f_u & f_v & f_w \\ g_u & g_v & g_w \\ h_u & h_v & h_w \end{vmatrix}$$

$$D_1 = \begin{vmatrix} g_v & g_w \\ h_v & h_w \end{vmatrix} \quad D_2 = \begin{vmatrix} f_v & f_w \\ h_v & h_w \end{vmatrix} \quad D_3 = \begin{vmatrix} f_v & f_w \\ g_v & g_w \end{vmatrix}$$

$$\text{由Cramer法则} \quad \frac{\partial u}{\partial x} = \frac{\begin{vmatrix} 1 & f_v & f_w \\ 0 & g_v & g_w \\ 0 & h_v & h_w \end{vmatrix}}{\begin{vmatrix} f_u & f_v & f_w \\ g_u & g_v & g_w \\ h_u & h_v & h_w \end{vmatrix}} = \frac{\begin{vmatrix} g_v & g_w \\ h_v & h_w \end{vmatrix}}{\begin{vmatrix} f_u & f_v & f_w \\ g_u & g_v & g_w \\ h_u & h_v & h_w \end{vmatrix}} = \frac{D_1}{D} \quad \text{同理 } \frac{\partial u}{\partial y} = -\frac{D_2}{D} \quad \frac{\partial u}{\partial z} = \frac{D_3}{D}$$

29. 三个方程分别对 x 求导

(注意 u 是关于 x 的一元函数, 故 y, z 均是 x 的函数)

$$\begin{cases} \frac{du}{dx} = f_x + f_y \frac{dy}{dx} + f_z \frac{dz}{dx} \\ 0 = g_x + g_y \frac{dy}{dx} + g_z \frac{dz}{dx} \\ 0 = h_x + h_y \frac{dy}{dx} + h_z \frac{dz}{dx} \end{cases} \Rightarrow \begin{cases} \frac{dy}{dx} = \frac{g_z h_x - g_x h_z}{g_y h_z - g_z h_y} \\ \frac{dz}{dx} = \frac{g_x h_y - g_y h_x}{g_y h_z - g_z h_y} \end{cases}$$

代入第一个方程

$$\frac{du}{dx} = \frac{f_x (g_y h_z - g_z h_y) + f_y (g_z h_x - g_x h_z) + f_z (g_x h_y - g_y h_x)}{g_y h_z - g_z h_y}$$

$$= \frac{\begin{vmatrix} f_x & f_y & f_z \\ g_x & g_y & g_z \\ h_x & h_y & h_z \end{vmatrix}}{\begin{vmatrix} g_y & g_z \\ h_y & h_z \end{vmatrix}}$$



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A30. 使用数学归纳法证明:

① $n=1$ 时. $\left(\frac{\partial u}{\partial y} = \varphi(z) \frac{\partial u}{\partial x}\right)$ 目标: 证明

$$\Rightarrow \begin{cases} \frac{\partial z}{\partial x} = 1 + y \varphi'(z) \frac{\partial z}{\partial x} \\ \frac{\partial z}{\partial y} = \varphi(z) + y \varphi'(z) \frac{\partial z}{\partial y} \end{cases}$$

$$\Rightarrow \frac{\partial z}{\partial x} = \frac{1}{1 - y \varphi'(z)} \quad \frac{\partial z}{\partial y} = \frac{\varphi(z)}{1 - y \varphi'(z)} \quad \left(\frac{\partial z}{\partial y} = \frac{\partial z}{\partial x} \cdot \varphi(z)\right)$$

$$\Rightarrow \frac{\partial u}{\partial y} = \varphi(z) \frac{\partial u}{\partial x} \text{ 结论成立.}$$

② 假设 $n=k$ 时. $\frac{\partial^k u}{\partial y^k} = \frac{\partial^{k-1}}{\partial x^{k-1}} \left[\varphi^k(z) \frac{\partial u}{\partial x} \right]$

$$\begin{aligned} \therefore \frac{\partial^{k+1} u}{\partial y^{k+1}} &= \frac{\partial}{\partial y} \left(\frac{\partial^k u}{\partial y^k} \right) = \frac{\partial}{\partial y} \left[\frac{\partial^{k-1}}{\partial x^{k-1}} \left(\varphi^k(z) \frac{\partial u}{\partial x} \right) \right] \\ &= \frac{\partial^{k-1}}{\partial x^{k-1}} \left[\frac{\partial}{\partial y} \left(\varphi^k(z) \frac{\partial u}{\partial x} \right) \right] \end{aligned}$$

$$\frac{\partial}{\partial x} \left(\frac{\partial u}{\partial y} \right) = \frac{\partial}{\partial x} \left(\varphi(z) \frac{\partial u}{\partial x} \right)$$

$$= \frac{\partial^{k-1}}{\partial x^{k-1}} \left[k \varphi^{k-1}(z) \varphi'(z) \frac{\partial z}{\partial y} \cdot \frac{\partial u}{\partial x} + \varphi^k(z) \frac{\partial^2 u}{\partial x \partial y} \right]$$

$$= \frac{\partial^{k-1}}{\partial x^{k-1}} \left[k \varphi^{k-1}(z) \varphi'(z) \frac{\partial z}{\partial x} \cdot \frac{\partial u}{\partial x} + \varphi^k(z) \varphi'(z) \frac{\partial z}{\partial x} \cdot \frac{\partial u}{\partial x} + \varphi^k(z) \varphi(z) \frac{\partial^2 u}{\partial x^2} \right]$$

$$= \frac{\partial^{k-1}}{\partial x^{k-1}} \left[k \varphi^k(z) \varphi'(z) \frac{\partial z}{\partial x} \cdot \frac{\partial u}{\partial x} + \varphi^{k+1}(z) \frac{\partial^2 u}{\partial x^2} \right]$$

$$= \frac{\partial^{k-1}}{\partial x^{k-1}} \left[(k+1) \varphi^k \varphi'(z) \frac{\partial z}{\partial x} \cdot \frac{\partial u}{\partial x} + \varphi^{k+1}(z) \frac{\partial^2 u}{\partial x^2} \right]$$

$$\star \hookrightarrow = \frac{\partial^{k-1}}{\partial x^{k-1}} \frac{\partial}{\partial x} \left[\varphi^{k+1}(z) \frac{\partial u}{\partial x} \right] = \frac{\partial^k}{\partial x^k} \left[\varphi^{k+1}(z) \frac{\partial u}{\partial x} \right]$$

$\therefore n=k+1$ 时也成立



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$$\begin{aligned}
 31. \quad Z_x &= \alpha + \alpha_x \cdot x + \varphi'(\alpha) \cdot \alpha_x \cdot y + \psi'(\alpha) \cdot \alpha_x = \alpha + \alpha_x (\underbrace{x + \varphi'(\alpha) y + \psi'(\alpha)}_{=0}) = \alpha \\
 Z_y &= \alpha_y \cdot x + \varphi'(\alpha) \cdot \alpha_y \cdot y + \varphi(\alpha) + \psi'(\alpha) \alpha_y = \varphi(\alpha) + \alpha_y (\underbrace{x + \varphi'(\alpha) y + \psi'(\alpha)}_{=0}) = \varphi(\alpha) \\
 \therefore Z_{xx} &= \alpha_x \quad Z_{xy} = \alpha_y \quad Z_{yx} = \varphi'(\alpha) \cdot \alpha_x \quad Z_{yy} = \psi'(\alpha) \cdot \alpha_y \\
 \therefore Z_{xx} \cdot Z_{yy} - (Z_{xy})^2 &= Z_{xx} \cdot Z_{yy} - Z_{xy} \cdot Z_{yx} = \varphi'(\alpha) \alpha_x \alpha_y - \varphi'(\alpha) \alpha_x \alpha_y = 0.
 \end{aligned}$$

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$$\begin{cases} \frac{\partial u}{\partial x} = \frac{\partial u}{\partial \xi} \cdot \frac{\partial \xi}{\partial x} + \frac{\partial u}{\partial \eta} \cdot \frac{\partial \eta}{\partial x} = \frac{\partial u}{\partial \xi} + \frac{\partial u}{\partial \eta} \\ \frac{\partial u}{\partial y} = \frac{\partial u}{\partial \xi} \cdot \frac{\partial \xi}{\partial y} + \frac{\partial u}{\partial \eta} \cdot \frac{\partial \eta}{\partial y} = \lambda_1 \frac{\partial u}{\partial \xi} + \lambda_2 \frac{\partial u}{\partial \eta} \end{cases}$$

$$\Rightarrow \frac{\partial^2 u}{\partial x^2} = \left[\frac{\partial^2 u}{\partial \xi^2} \frac{\partial \xi}{\partial x} + \frac{\partial^2 u}{\partial \xi \partial \eta} \frac{\partial \eta}{\partial x} \right] + \left[\frac{\partial^2 u}{\partial \eta \partial \xi} \frac{\partial \xi}{\partial x} + \frac{\partial^2 u}{\partial \eta^2} \frac{\partial \eta}{\partial x} \right]$$

$$= \frac{\partial^2 u}{\partial \xi^2} + 2 \frac{\partial^2 u}{\partial \xi \partial \eta} + \frac{\partial^2 u}{\partial \eta^2} \quad ①$$

$$\Rightarrow \frac{\partial^2 u}{\partial x \partial y} = \left[\frac{\partial^2 u}{\partial \xi^2} \frac{\partial \xi}{\partial y} + \frac{\partial^2 u}{\partial \xi \partial \eta} \frac{\partial \eta}{\partial y} \right] + \left[\frac{\partial^2 u}{\partial \eta \partial \xi} \frac{\partial \xi}{\partial y} + \frac{\partial^2 u}{\partial \eta^2} \frac{\partial \eta}{\partial y} \right]$$

$$= \lambda_1 \frac{\partial^2 u}{\partial \xi^2} + (\lambda_1 + \lambda_2) \frac{\partial^2 u}{\partial \xi \partial \eta} + \lambda_2 \frac{\partial^2 u}{\partial \eta^2} \quad ②$$

$$\Rightarrow \frac{\partial^2 u}{\partial y^2} = \lambda_1 \left[\frac{\partial^2 u}{\partial \xi^2} \frac{\partial \xi}{\partial y} + \frac{\partial^2 u}{\partial \xi \partial \eta} \frac{\partial \eta}{\partial y} \right] + \lambda_2 \left[\frac{\partial^2 u}{\partial \xi \partial \eta} \frac{\partial \xi}{\partial y} + \frac{\partial^2 u}{\partial \eta^2} \frac{\partial \eta}{\partial y} \right]$$

$$= \lambda_1^2 \frac{\partial^2 u}{\partial \xi^2} + 2\lambda_1 \lambda_2 \frac{\partial^2 u}{\partial \xi \partial \eta} + \lambda_2^2 \frac{\partial^2 u}{\partial \eta^2} \quad ③$$

① + 2② + ③ 代入合并得

$$\underbrace{(A + 2B\lambda_1 + C\lambda_1^2)}_{\text{全为0}} \frac{\partial^2 u}{\partial \xi^2} + \underbrace{(2A + 2B(\lambda_1 + \lambda_2) + 2C\lambda_1 \lambda_2)}_{\text{全为0}} \frac{\partial^2 u}{\partial \xi \partial \eta} + \underbrace{(A + 2B\lambda_2 + C\lambda_2^2)}_{\text{全为0}} \frac{\partial^2 u}{\partial \eta^2} = 0$$

$\therefore \lambda_1, \lambda_2$ 是 $C\lambda^2 + 2B\lambda + A = 0$ 的根 ($B^2 - AC > 0$)

且 $\lambda_1 \neq \lambda_2$

(若 $\lambda_1 = \lambda_2$, 也为0, 舍去)



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33.

$$(1) \quad \frac{\partial w}{\partial x} = \frac{1}{z} \cdot \frac{\partial z}{\partial x} - 1 \quad \frac{\partial w}{\partial y} = \frac{1}{z} \cdot \frac{\partial z}{\partial y} - 1 \quad \frac{\partial z}{\partial x} = z \cdot \frac{\partial w}{\partial x} + z \quad \frac{\partial z}{\partial y} = z \cdot \frac{\partial w}{\partial y} + z$$

$$\therefore yz \frac{\partial w}{\partial x} - xz \frac{\partial w}{\partial y} + (y-xz)(y-xz) \quad \therefore z(y \frac{\partial w}{\partial x} - x \frac{\partial w}{\partial y}) = 0$$

$$\text{若 } z \neq 0 \text{ 有 } x \frac{\partial w}{\partial y} = y \frac{\partial w}{\partial x} \quad (\text{若 } z=0 \text{ 也成立}) \quad \text{对于 } w = w(u, v)$$

$$\therefore \frac{\partial w}{\partial x} = \frac{\partial w}{\partial u} \cdot \frac{\partial u}{\partial x} + \frac{\partial w}{\partial v} \cdot \frac{\partial v}{\partial x} = 2x \frac{\partial w}{\partial u} - \frac{1}{x^2} \cdot \frac{\partial w}{\partial v}$$

$$\frac{\partial w}{\partial y} = \frac{\partial w}{\partial u} \cdot \frac{\partial u}{\partial y} + \frac{\partial w}{\partial v} \cdot \frac{\partial v}{\partial y} = 2y \frac{\partial w}{\partial u} - \frac{1}{y^2} \frac{\partial w}{\partial v}$$

$$\therefore 2xy \frac{\partial w}{\partial u} - \frac{x}{y^2} \frac{\partial w}{\partial v} = 2xy \frac{\partial w}{\partial u} - \frac{y}{x^2} \frac{\partial w}{\partial v} \Rightarrow (x^3 - y^3) \frac{\partial w}{\partial v} = 0$$

$$\text{若 } y \neq x \text{ 有 } \frac{\partial w}{\partial v} = 0 \quad (\text{若 } y=x \text{ 也成立})$$

$$(2) \quad \frac{\partial w}{\partial y} = -1 + x \cdot \frac{\partial z}{\partial y} \quad \therefore \frac{\partial z}{\partial y} = \frac{1}{x} + \frac{\partial w}{x \partial y} \quad \therefore \frac{\partial^2 z}{\partial y^2} = \frac{\partial^2 w}{x \partial y^2}$$

$$\therefore \frac{y}{x} \frac{\partial^2 w}{\partial y^2} + \frac{z}{x} \left(\frac{\partial w}{\partial y} + 1 \right) = \frac{z}{x} \quad \text{即 } y \frac{\partial^2 w}{\partial y^2} + 2 \frac{\partial w}{\partial y} = 0$$

$$y \neq 0 \text{ 时, } \frac{\partial w}{\partial y} = \frac{\partial w}{\partial u} \cdot \frac{\partial u}{\partial y} + \frac{\partial w}{\partial v} \cdot \frac{\partial v}{\partial y} = -\frac{u}{y} \frac{\partial w}{\partial u}$$

$$\frac{\partial^2 w}{\partial y^2} = \frac{u}{y^2} \frac{\partial w}{\partial u} - \frac{1}{y} \frac{\partial u}{\partial y} \frac{\partial w}{\partial u} + \frac{\partial w}{\partial v} \cdot \frac{\partial v}{\partial y}$$

$$= -\frac{u}{y} \left(\frac{\partial^2 w}{\partial u^2} \frac{\partial u}{\partial y} + \frac{\partial^2 w}{\partial v \partial u} \cdot \frac{\partial v}{\partial y} \right) = \frac{zu}{y^2} \frac{\partial w}{\partial u} + \frac{u^2}{y^2} \frac{\partial^2 w}{\partial u^2}$$

$$\Rightarrow \frac{zu}{y} \cdot \frac{\partial w}{\partial u} + \frac{u^2}{y} \cdot \frac{\partial^2 w}{\partial u^2} - \frac{zu}{y} \cdot \frac{\partial w}{\partial u} = 0$$

$$\text{即 } \frac{u^2}{y} \cdot \frac{\partial^2 w}{\partial u^2} = 0 \quad (u \neq 0 \text{ 时 } \Rightarrow \frac{\partial^2 w}{\partial u^2} = 0) \Rightarrow \frac{\partial^2 w}{\partial u^2} = 0$$



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34.

$$\because p = z_x, q = z_y$$

$$\therefore W_p = x + p x_p + q y_p - (z_x \cdot x_p + z_y \cdot y_p) = x + p x_p + q y_p - p x_p - q y_p = x$$

$$W_q = p x_q + y + q y_q - (z_x \cdot x_q + z_y \cdot y_q) = y + p x_q + q y_q - p x_q - q y_q = y$$

$$\text{记 } W_p(p, q) = W_p(p(x, y), q(x, y))$$

$$\therefore W_p = x$$

$$\begin{array}{c} x \\ \swarrow \quad \searrow \\ p \quad q \\ \swarrow \quad \searrow \\ W \quad \end{array}$$

$$\text{两边对 } x \text{ 求导: } W_{pp} \cdot p_x + W_{pq} \cdot q_x = 1$$

$$\therefore W_{pp} \cdot z_{xx} + W_{pq} \cdot z_{yx} = W_{pp} z_{xx} + W_{pq} \cdot z_{xy} = 1 \dots \textcircled{1}$$

$$\text{两边对 } y \text{ 求导: } W_{pp} \cdot p_y + W_{pq} \cdot q_y = 0$$

$$\therefore W_{pp} \cdot z_{xy} + W_{pq} \cdot z_{yy} = 0$$

..... ②

$$\text{记 } W_q(p, q) = W_q(p(x, y), q(x, y))$$

$$\therefore W_q = y$$

$$\begin{array}{c} x \\ \swarrow \quad \searrow \\ p \quad q \\ \swarrow \quad \searrow \\ W \quad \end{array}$$

$$\text{两边对 } x \text{ 求导: } W_{qp} \cdot p_x + W_{qq} \cdot q_x = 0$$

$$\therefore W_{qp} \cdot z_{xx} + W_{qq} \cdot z_{yx} = W_{qp} \cdot z_{xx} + W_{qq} \cdot z_{xy} = 0 \dots \textcircled{3}$$

$$\text{两边对 } y \text{ 求导: } W_{qp} \cdot p_y + W_{qq} \cdot q_y = 1$$

$$\therefore W_{qp} \cdot z_{xy} + W_{qq} \cdot z_{yy} = W_{qp} \cdot z_{xy} + W_{qq} \cdot z_{yy} = 1 \dots \textcircled{4}$$

$$\textcircled{1} \textcircled{2} \textcircled{3} \textcircled{4} \Leftrightarrow \begin{pmatrix} z_{xx} & z_{xy} \\ z_{xy} & z_{yy} \end{pmatrix} \begin{pmatrix} W_{pp} & W_{pq} \\ W_{pq} & W_{qq} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$



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35. $P: x+y+xy=1 \quad (1+x)y=1-x \quad y=\frac{1-x}{1+x} \quad y_x = \frac{-2}{(1+x)^2} = -\frac{1+y}{1+x}$

切线方程为 $y-y_0 = -\frac{1+y_0}{1+x_0}(x-x_0)$

即 $y = -\frac{1+y_0}{1+x_0}(x-x_0) + y_0$

36. $x_t=1 \quad y_t=2t \quad z_t=3t^2 \quad \text{记 } \vec{v} = (1, 2t, 3t^2)$

记曲线上任一点 (t_0, t_0^2, t_0^3)

切线方程为 $\frac{x-t_0}{1} = \frac{y-t_0^2}{2t_0} = \frac{z-t_0^3}{3t_0^2}$

平面 $x+2y+z=4$ 的法向 $\vec{n}=(1, 2, 1)$

令 $\vec{n} \cdot \vec{v}|_{t_0} = 1+4t_0+3t_0^2=0 \quad \therefore t_0 = -1 \text{ 或 } -\frac{1}{3}$

$\therefore (-1, 1, -1)$ 与 $(-\frac{1}{3}, \frac{1}{9}, -\frac{1}{27})$ 两点符合条件.

37. 记 $F(x, y, z) = xyz - a^3 = 0 \quad \frac{\partial F}{\partial x} = yz \quad \frac{\partial F}{\partial y} = xz \quad \frac{\partial F}{\partial z} = xy$

曲面上任一点 $P_0(x_0, y_0, z_0)$ 的切向为 $(y_0 z_0, x_0 z_0, x_0 y_0)$.

切平面为 $y_0 z_0(x-x_0) + x_0 z_0(y-y_0) + x_0 y_0(z-z_0) = 0$

\therefore 四面体四棱长分别为 $(0, 0, 0), (0, 0, 3z_0), (0, 3y_0, 0), (3x_0, 0, 0)$

$V = \frac{1}{3} \times \frac{1}{2} |3x_0 \cdot 3y_0| \times |3z_0| = \frac{9}{2} |x_0 y_0 z_0| = \frac{9}{2} a^3$ 为常数.

得证.



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38. 记 $f(x, y, z) = \sqrt{x} + \sqrt{y} + \sqrt{z} - \sqrt{a} = 0$

$$f_x = \frac{1}{2\sqrt{x}} \quad f_y = \frac{1}{2\sqrt{y}} \quad f_z = \frac{1}{2\sqrt{z}}$$

曲面上任一点 (x_0, y_0, z_0) 的切平面为 $\frac{x-x_0}{\sqrt{x_0}} + \frac{y-y_0}{\sqrt{y_0}} + \frac{z-z_0}{\sqrt{z_0}} = 0$

$$\therefore \frac{x}{\sqrt{x_0}} + \frac{y}{\sqrt{y_0}} + \frac{z}{\sqrt{z_0}} = \sqrt{x_0} + \sqrt{y_0} + \sqrt{z_0}$$

$$\therefore \frac{x}{\sqrt{x_0}(\sqrt{x_0} + \sqrt{y_0} + \sqrt{z_0})} + \frac{y}{\sqrt{y_0}(\sqrt{x_0} + \sqrt{y_0} + \sqrt{z_0})} + \frac{z}{\sqrt{z_0}(\sqrt{x_0} + \sqrt{y_0} + \sqrt{z_0})} = 1$$

\therefore 曲面在 x, y, z 轴下截距分别为 $\sqrt{x_0}(\sqrt{x_0} + \sqrt{y_0} + \sqrt{z_0}), \sqrt{y_0}(\sqrt{x_0} + \sqrt{y_0} + \sqrt{z_0}), \sqrt{z_0}(\sqrt{x_0} + \sqrt{y_0} + \sqrt{z_0})$

\therefore 截距和为 $(\sqrt{x_0} + \sqrt{y_0} + \sqrt{z_0})^2 = a$

39. 记 $F = x^2 + y^2 - a^2 \quad G = z - xy$

$$\vec{l}_F = (F_x, F_y, F_z) = (2x, 2y, 0) \quad \vec{l}_G = (-y, -x, 1)$$

对 F 与 G 任一交点 $P_0(x_0, y_0, z_0)$, $\begin{cases} x_0^2 + y_0^2 = a^2 \\ z_0 = x_0 y_0 \end{cases}$

$$\cos \langle \vec{l}_F, \vec{l}_G \rangle = \frac{\vec{l}_F \cdot \vec{l}_G}{|\vec{l}_F| |\vec{l}_G|} = \frac{-2x_0 y_0}{\sqrt{x_0^2 + y_0^2} \cdot \sqrt{x_0^2 + y_0^2 + 1}} = \frac{-2z_0}{a\sqrt{a^2 + 1}}$$

\therefore 在 $P_0(x_0, y_0, z_0)$ 处夹角为 $\arccos\left(-\frac{2z_0}{a\sqrt{a^2 + 1}}\right)$ 或 $\arccos \frac{2z_0}{a\sqrt{a^2 + 1}}$



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40. 证: 记 $F(x, y) = f(x, y) - g(x, y)$.

\therefore 对 $\forall (x, y) \in \partial D$ 有 $f = g$. 即: 在闭域 D 的边界上, $F = 0$

在 D 的内部即 D° :

① 若对 $\forall (x_0, y_0) \in D^\circ$ 有 $F(x_0, y_0) \geq 0$. 显然结论成立

② 若 $\exists (x_0, y_0) \in D^\circ$ 使 $F(x_0, y_0) \neq 0$.

1° 若 $F(x_0, y_0) > 0$ 则 D° 中能取到 F 的最大值

$\therefore D^\circ$ 中能取到 F 的极大值 $\therefore F_x = F_y = 0$ 即 $\nabla F(x_0) = 0$

$\therefore \nabla f(x_0) = \nabla g(x_0)$

2° 若 $F(x_0, y_0) < 0$ 则 D° 中能取到 F 的最小值

$\therefore D^\circ$ 中能取到 F 的极小值 $\therefore F_x = F_y = 0$ 即 $\nabla F(x_0) = 0$

$\therefore \nabla f(x_0) = \nabla g(x_0)$

41. [引理]. f 是凸函数 \Rightarrow 对 $\forall x_1, x_2 \in D$, 有 $f(x_2) - f(x_1) \geq \text{grad } f(x_1) \cdot \frac{x_2 - x_1}{\|x_2 - x_1\|} = \langle \nabla f(x_1), \frac{x_2 - x_1}{\|x_2 - x_1\|} \rangle$

(证明: \Rightarrow : f 是 D 上凸函数 $\therefore \forall x_1, x_2 \in D$ 及 $t \in (0, 1)$ 有 $f(tx_2 + (1-t)x_1) \leq tf(x_2) + (1-t)f(x_1)$

即 $\frac{f(tx_2 + (1-t)x_1) - f(x_1)}{t} \leq f(x_2) - f(x_1)$ 令 $t \rightarrow 0$. 左式 $= \frac{\partial f}{\partial t} \Big|_{x_1} = \nabla f(x_1) \cdot \frac{x_2 - x_1}{\|x_2 - x_1\|}$

(其逆命题也成立, 可自行证明)

证: $\because x_0$ 是 $f(x)$ 临界点 $\therefore \nabla f(x_0) = 0$.

\therefore 对 $\forall x \in \mathbb{R}^n$. $\because f$ 是凸函数.

由引理 $f(x) - f(x_0) \geq \langle \nabla f(x_0), \frac{x - x_0}{\|x - x_0\|} \rangle = \langle 0, \frac{x - x_0}{\|x - x_0\|} \rangle = 0$

对 $\forall x \in \mathbb{R}^n$ 有 $f(x) \geq f(x_0)$ $\therefore x_0$ 是 $f(x)$ 最小值点



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42. 在 (x_0, y_0) 点对函数作 Taylor 展开. 对 $\forall (x, y)$

$$f(x, y) - f(x_0, y_0) = \nabla f(x_0, y_0) + \frac{1}{2} (x - x_0, y - y_0) \cdot H_f(x_0, y_0) \begin{pmatrix} x - x_0 \\ y - y_0 \end{pmatrix}$$

取极值 $= 0$

(f 是二元函数 \Rightarrow 三阶及以上偏导均为 0)

不妨设 f 取到极大值于 x_0 点, 则 $H_f \leq 0 \quad \therefore \forall f(x, y) - f(x_0, y_0) \leq 0$

$\therefore f$ 在 (x_0, y_0) 处取得 max.

43. $f_x = -(1+e^y)\sin x = 0 \quad f_y = \cos x e^y - (y+1)e^y \quad$ 当 $\nabla f = 0$

$$\begin{cases} (1+e^y)\sin x = 0 \\ \cos x e^y = (y+1)e^y \end{cases} \Rightarrow \begin{cases} x_1 = 2k\pi \\ y_1 = 0 \end{cases} \text{ 或 } \begin{cases} x_2 = (2k+1)\pi \\ y_2 = -2 \end{cases}$$

$$\therefore f_{xx} = -(1+e^y)\cos x \quad f_{xy} = -\sin x e^y \quad f_{yy} = \cos x e^y - (y+2)e^y$$

1) 在 $(2k\pi, 0)$ 点 $f_{xx} \cdot f_{yy} - f_{xy}^2 = (-2) \cdot (-1) - 0 = 2 > 0, \quad f_{xx} = -2 < 0$

$\therefore H_f(x_1) < 0 \quad \therefore f$ 在 $\forall (2k\pi, 0) \quad (k \in \mathbb{Z})$ 上取得极大值.

2) 在 $((2k+1)\pi, -2)$ 点 $f_{xx} \cdot f_{yy} - f_{xy}^2 = (1+\frac{1}{e^2}) \cdot \frac{-1}{e^2} < 0$ 不取极值

$\therefore f$ 有无穷多个极大值但无极小值.

44. 若 $f(x, y)$ 在 \mathbb{R}^2 上存在点 (x_0, y_0) 使 $f(x_0, y_0)$ 为 f 极大值

$$\therefore (x_0, y_0) \text{ 能使: } \begin{cases} f_{xx} f_{yy} - f_{xy}^2 \geq 0 \\ f_{xx} \leq 0 \end{cases}$$

\therefore 由条件 $f_{xx} + f_{yy} > 0$ 又 $f_{xx} \leq 0 \quad \therefore f_{yy} > 0 \quad \therefore f_{xx} \cdot f_{yy} < 0$

又 $\therefore f_{xy}^2 \geq 0 \quad \therefore f_{xx} f_{yy} - f_{xy}^2 > 0 \quad \therefore f_{xx} f_{yy} = f_{xy} = 0$

此时 f 在 (x_0, y_0) 显然不取得极值, 矛盾

$\therefore f$ 无极大值点



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45.

STEP 1 $\begin{cases} \sigma_a = \sum_{i=1}^n 2x_i(ax_i + b - y_i) = 0 \\ \sigma_b = -\sum_{i=1}^n 2(ax_i + b - y_i) = 0 \end{cases} \Rightarrow \begin{cases} \left(\sum_{i=1}^n x_i^2\right)a + \left(\sum_{i=1}^n x_i\right)b = \sum_{i=1}^n x_i y_i \\ \left(\sum_{i=1}^n x_i\right)a + nb = \sum_{i=1}^n y_i \end{cases}$

$\therefore \begin{pmatrix} \sum_{i=1}^n x_i^2 & \sum_{i=1}^n x_i \\ \sum_{i=1}^n x_i & n \end{pmatrix}$ 是实对称矩阵, 故其可逆

$\therefore n \sum_{i=1}^n x_i^2 > \left(\sum_{i=1}^n x_i\right)^2$ (由 Cauchy-Schwarz 不等式)

$\sum_{i=1}^n x_i = \left(\sum_{i=1}^n 1 \cdot x_i\right) < \left(\sum_{i=1}^n 1^2\right)^{\frac{1}{2}} \left(\sum_{i=1}^n x_i^2\right)^{\frac{1}{2}}$ (由 Hölder 不等式)

$\therefore \det \begin{pmatrix} \sum_{i=1}^n x_i^2 & \sum_{i=1}^n x_i \\ \sum_{i=1}^n x_i & n \end{pmatrix} > 0$ 又 $\sum_{i=1}^n x_i^2 > 0$ 故此矩阵正定

\therefore 临界点 $\begin{pmatrix} a_0 \\ b_0 \end{pmatrix} = \begin{pmatrix} \sum_{i=1}^n x_i^2 & \sum_{i=1}^n x_i \\ \sum_{i=1}^n x_i & n \end{pmatrix}^{-1} \begin{pmatrix} \sum_{i=1}^n x_i y_i \\ \sum_{i=1}^n y_i \end{pmatrix}$

STEP 2 证 σ 在 $\begin{pmatrix} a_0 \\ b_0 \end{pmatrix}$ 取到 min

① 当 $\left\| \begin{pmatrix} a \\ b \end{pmatrix} \right\| \rightarrow +\infty$ 时, $\sigma(a, b) \rightarrow +\infty$

$\exists L > 0 \Rightarrow \sigma(a, b)$ 在 $\left\{ \begin{pmatrix} a \\ b \end{pmatrix} : \left\| \begin{pmatrix} a \\ b \end{pmatrix} \right\| \leq L \right\}$ 上取到 min

② $\begin{pmatrix} a_0 \\ b_0 \end{pmatrix}$ 是 σ 的唯一临界点

由 ①②, σ 在 $\begin{pmatrix} a_0 \\ b_0 \end{pmatrix}$ 取到 min

记 $D = \begin{vmatrix} \sum x_i^2 & \sum x_i \\ \sum x_i & n \end{vmatrix}$ $D_1 = \begin{vmatrix} \sum x_i y_i & \sum x_i \\ \sum y_i & n \end{vmatrix}$ $D_2 = \begin{vmatrix} \sum x_i^2 & \sum x_i y_i \\ \sum x_i & \sum y_i \end{vmatrix}$

若 $D \neq 0$, $a_0 = \frac{D_1}{D}$, $b_0 = \frac{D_2}{D}$



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46. 记 $h(x) = \int \frac{1}{(1+x^2)^2} dx$

$$\begin{aligned} \therefore \int (ax+b-\frac{1}{1+x^2})^2 dx &= \int (a^2x^2 + b^2 + \frac{1}{(1+x^2)^2} + 2abx - \frac{2b}{1+x^2} - \frac{2ax}{1+x^2}) dx \\ &= \frac{a^2}{3}x^3 + b^2x + abx^2 - 2b \arctan x - a \ln(1+x^2) + h(x) + C \end{aligned}$$

$$\therefore \int_0^1 (ax+b-\frac{1}{1+x^2})^2 dx = \frac{a^2}{3} + b^2 + ab - \frac{\pi}{2}b - a \ln 2 + h(1) - h(0) \triangleq g(a,b)$$

$$\begin{cases} g_a = \frac{2}{3}a + b - \ln 2 = 0 \\ g_b = 2b - \frac{\pi}{2} + a = 0 \end{cases} \Rightarrow \begin{cases} a = 6\ln 2 - \frac{3}{2}\pi \\ b = \pi - 3\ln 2 \end{cases}$$

经检验, f 在 $(6\ln 2 - \frac{3}{2}\pi, \pi - 3\ln 2)$ 取得极小值, 即取得最小值.

47. 记 $f(a,b,c) = \sum_{i=1}^n (ax_i^2 + bx_i + c - y_i)^2$

$$\therefore f_a = 2 \sum_{i=1}^n x_i^2 (ax_i^2 + bx_i + c - y_i) \quad f_b = 2 \sum_{i=1}^n x_i (ax_i^2 + bx_i + c - y_i) \quad f_c = 2 \sum_{i=1}^n (ax_i^2 + bx_i + c - y_i)$$

$$\begin{cases} f_a = f_b = f_c = 0 \end{cases} \Rightarrow \begin{cases} a \sum x_i^4 + b \sum x_i^3 + c \sum x_i^2 = \sum x_i^2 y_i \\ a \sum x_i^3 + b \sum x_i^2 + c \sum x_i = \sum x_i y_i \\ a \sum x_i^2 + b \sum x_i + cn = \sum y_i \end{cases}$$

$$D = \begin{vmatrix} \sum x_i^4 & \sum x_i^3 & \sum x_i^2 \\ \sum x_i^3 & \sum x_i^2 & \sum x_i \\ \sum x_i^2 & \sum x_i & n \end{vmatrix}$$

$$D_1 = \begin{vmatrix} \sum x_i^2 y_i & \sum x_i^3 & \sum x_i^2 \\ \sum x_i y_i & \sum x_i^2 & \sum x_i \\ \sum y_i & \sum x_i & n \end{vmatrix}$$

$$D_2 = \begin{vmatrix} \sum x_i^4 & \sum x_i^2 y_i & \sum x_i^2 \\ \sum x_i^3 & \sum x_i y_i & \sum x_i \\ \sum x_i^2 & \sum y_i & n \end{vmatrix}$$

$$D_3 = \begin{vmatrix} \sum x_i^4 & \sum x_i^3 & \sum x_i^2 y_i \\ \sum x_i^3 & \sum x_i^2 & \sum x_i y_i \\ \sum x_i^2 & \sum x_i & \sum y_i \end{vmatrix}$$

$$\text{当 } D \neq 0 \text{ 时, } a = \frac{D_1}{D} \quad b = \frac{D_2}{D} \quad c = \frac{D_3}{D}$$

经检验, f 在 $(\frac{D_1}{D}, \frac{D_2}{D}, \frac{D_3}{D})$ 取得 \min .



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48.

$$\text{记 } F(x, y) = x^3 + y^3 - 3xy$$

$$\therefore F_x = 3x^2 - 3y \quad F_y = 3y^2 - 3x$$

$\therefore F, F_x, F_y$ 都是关于 x, y, z 的初等函数 且 $x \neq y^2$

$$\therefore \begin{cases} \textcircled{1} F, F_x, F_y \text{ 在 } B(x_0, y_0) \text{ 连续} \\ \textcircled{2} F(x_0, y_0) = 0 \\ \textcircled{3} F_y(x_0, y_0) \neq 0 \end{cases}$$

由隐函数存在定理, $F(x, y) = 0$ 可唯一确定函数 $y = y(x)$.

$$\text{且 } y'(x) = -\frac{F_x}{F_y} = \frac{y - x^2}{y^2 - x}$$

$$\text{令 } y(x) = 0 \quad \therefore \begin{cases} y - x^2 = 0 \\ x^3 + y^3 - 3xy = 0 \end{cases} \Rightarrow \begin{cases} x = \sqrt[3]{2} \\ y = \sqrt[3]{4} \end{cases}$$

$$\text{又 } y''(x) = \frac{(y(x) - 2x)(y^2 - x) - (y - x^2)(2y \cdot y'(x) - 1)}{(y^2 - x)^2} = \frac{-2\sqrt[3]{2}}{\sqrt[3]{16} - \sqrt[3]{2}} < 0$$

$\therefore y(x)$ 在 $x = \sqrt[3]{2}$ 处取得极大值 $\sqrt[3]{4}$.



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49. 记 $L(x_1, \dots, x_n) = \sum x_i^2 + \lambda(\sum a_i x_i - 1)$

$$\begin{cases} 2x_i + \lambda a_i = 0 \\ \sum_{i=1}^n a_i x_i = 1 \end{cases} \Rightarrow \lambda = \frac{-2}{\sum a_i^2} \quad \therefore x_i = \frac{a_i}{\sum a_i^2}$$

$\therefore H_f = \begin{pmatrix} 2 & & \\ & \ddots & \\ & & 2 \end{pmatrix} > 0$

$\therefore (\frac{a_1}{\sum a_i^2}, \frac{a_2}{\sum a_i^2}, \dots, \frac{a_n}{\sum a_i^2})$ 是其极小值点

$\therefore f_{\min} = f(\frac{a_1}{\sum a_i^2}, \dots, \frac{a_n}{\sum a_i^2}) = \frac{\sum a_i^2}{(\sum a_i^2)^2} = \frac{1}{\sum a_i^2}$

50. 记 $L(x_1, \dots, x_n) = \pi x_i^2 + \lambda(\sum x_i^2 - r^2)$

$$\begin{cases} 2\pi x_i + 2\lambda x_i = 0 \\ \sum x_i^2 = r^2 \end{cases} \Rightarrow \pi x_i^2 + \lambda x_i^2 = 0 \xRightarrow{n \text{ 个相加}} n \pi x_i^2 + \lambda(\sum x_i^2) = 0$$

$\therefore n \pi x_i^2 + \lambda r^2 = 0$

又 $\lambda = -\frac{\pi x_i^2}{x_i^2} \quad \therefore x_i^2 = \frac{r^2}{n} \quad (i=1, 2, \dots, n) \quad \therefore u_{\max} = u(\frac{r}{\sqrt{n}}, \dots, \frac{r}{\sqrt{n}}) = \frac{r^{2n}}{n^n}$

51. 记 $d = x^2 + y^2 + z^2$ 记 $L(x, y, z) = x^2 + y^2 + z^2 + \lambda(a_1 x + b_1 y + c_1 z - 1) + \mu(a_2 x + b_2 y + c_2 z - 1)$

$$\begin{cases} 2x + \lambda a_1 + \mu a_2 = 0 \\ 2y + \lambda b_1 + \mu b_2 = 0 \\ 2z + \lambda c_1 + \mu c_2 = 0 \\ a_1 x + b_1 y + c_1 z = 1 \\ a_2 x + b_2 y + c_2 z = 1 \end{cases}$$

设其解为 (x_0, y_0) $H_f = \begin{pmatrix} 2 & & \\ & 2 & \\ & & 2 \end{pmatrix} > 0 \quad \therefore f(x_0, y_0) = f_{\min}$

$\therefore d_{\min} = \sqrt{x_0^2 + y_0^2 + z_0^2} = \sqrt{-\frac{1}{2}(\lambda + \mu)} = \sqrt{\frac{a_1^2 + b_1^2 + c_1^2 + a_2^2 + b_2^2 + c_2^2 - 2(a_1 a_2 + b_1 b_2 + c_1 c_2)}{(a_1^2 + b_1^2 + c_1^2)(a_2^2 + b_2^2 + c_2^2) - (a_1 a_2 + b_1 b_2 + c_1 c_2)^2}}$

52. 记 $f(x, y, z) = \frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} - 1$ $\nabla f(x, y, z) = (\frac{2x}{a^2}, \frac{2y}{b^2}, \frac{2z}{c^2}) \quad \forall (x_0, y_0, z_0) \in I$ 卦限 $(x_0, y_0, z_0 \neq 0)$

切平面方程为: $\frac{2x_0}{a^2}(x - x_0) + \frac{2y_0}{b^2}(y - y_0) + \frac{2z_0}{c^2}(z - z_0) = 0$

分别令 x, y, z 中二者为零 得其与坐标轴交点 $(0, 0, \frac{c^2}{z_0})$ $(0, \frac{b^2}{y_0}, 0)$ $(\frac{a^2}{x_0}, 0, 0)$

\therefore 所求 $V = \frac{1}{3} \times (\frac{1}{2} \cdot \frac{a^2 b^2}{x_0 y_0}) \cdot \frac{c^2}{z_0} = \frac{a^2 b^2 c^2}{6 x_0 y_0 z_0}$

$(\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} \geq \sqrt[3]{\frac{x^2 y^2 z^2}{a^2 b^2 c^2}} \quad \therefore x y z \leq \frac{a b c}{\sqrt[3]{3}})$

$\therefore V \geq \frac{a^2 b^2 c^2}{6} \cdot \frac{\sqrt[3]{3}}{a b c} = \frac{\sqrt{3}}{2} a b c$