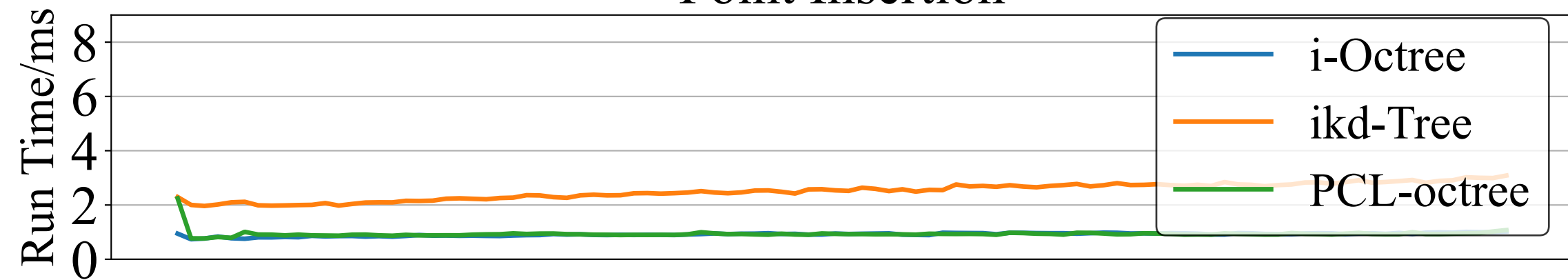
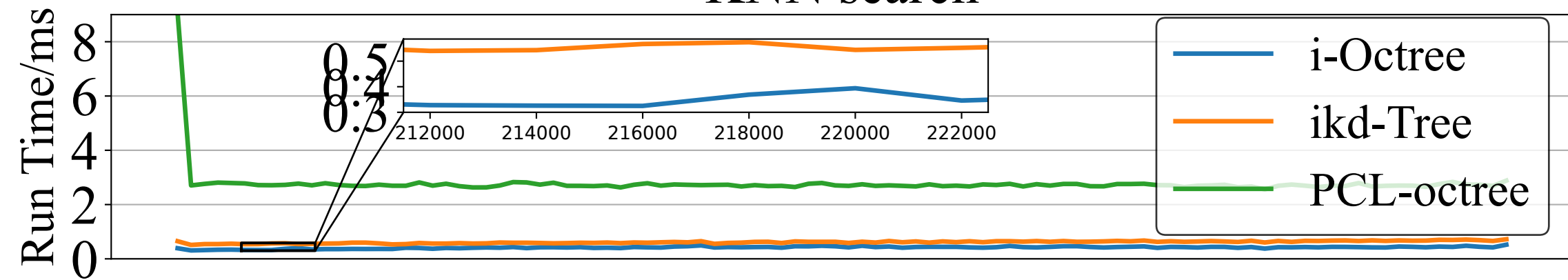


Point Insertion



KNN search



Radius Neighbors Search

